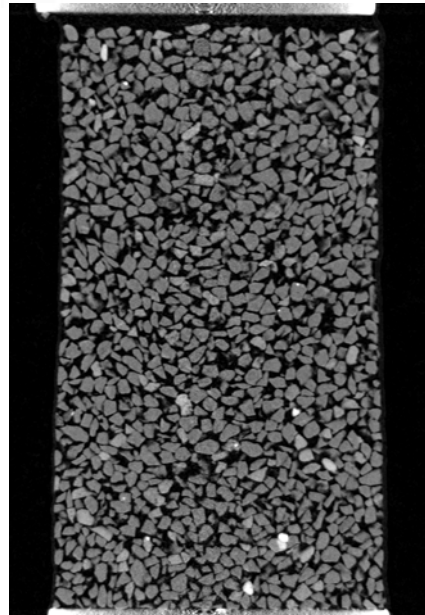
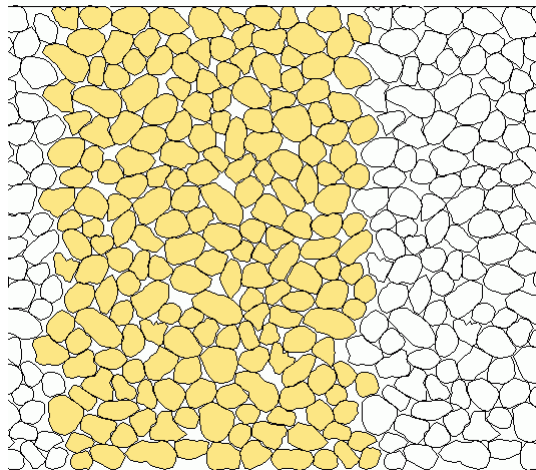
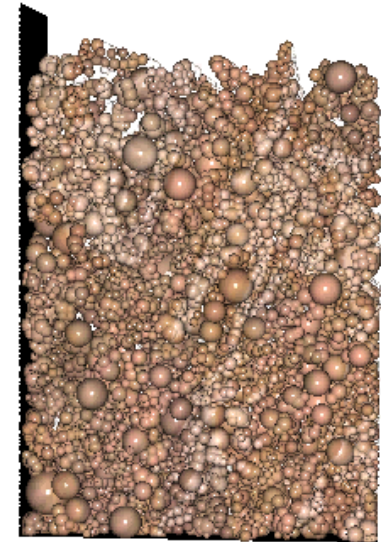


# Granular Mechanics of Geomaterials

(presentation in Cassino, Italy, 2006)

Takashi Matsushima

University of Tsukuba

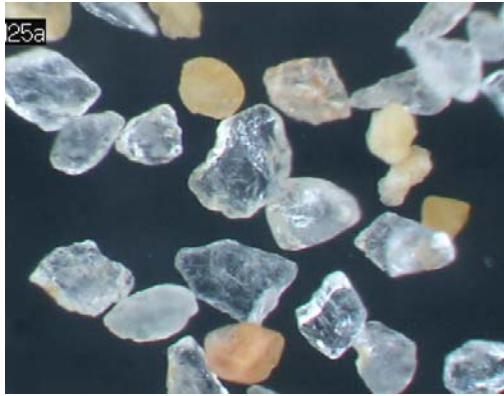


# Where am I from?

---



# What is granular mechanics?



**Particle characteristics**  
(size, shape, crushability etc.)



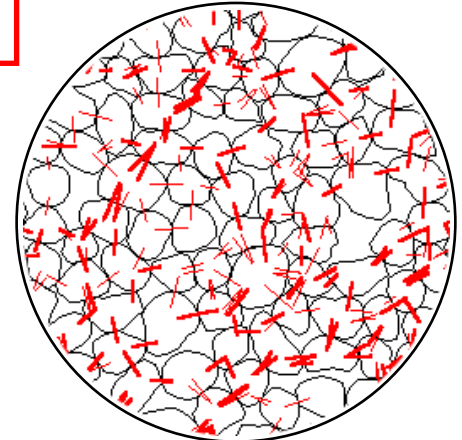
**Particle interaction**



**Direct simulation**  
(by DEM etc.)



**Constitutive model as  
solid or fluid**



**Simulation as continua**  
(by FEM, SPH etc.)

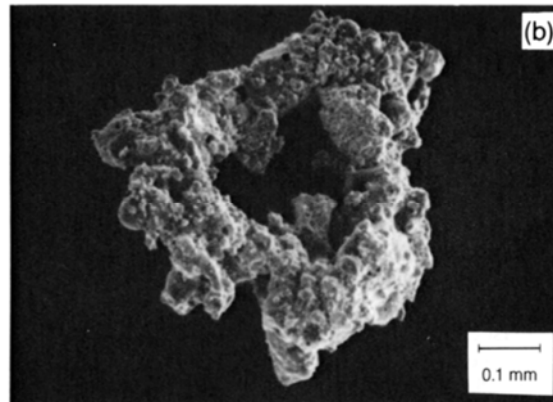
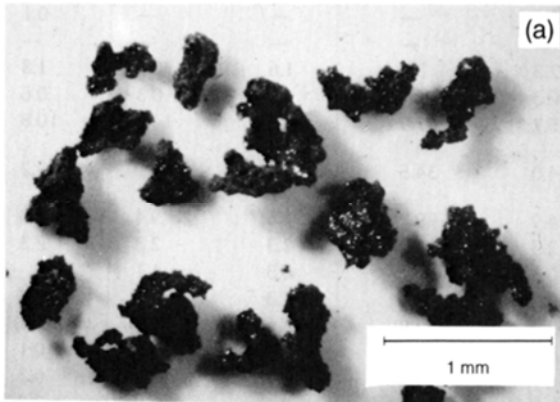
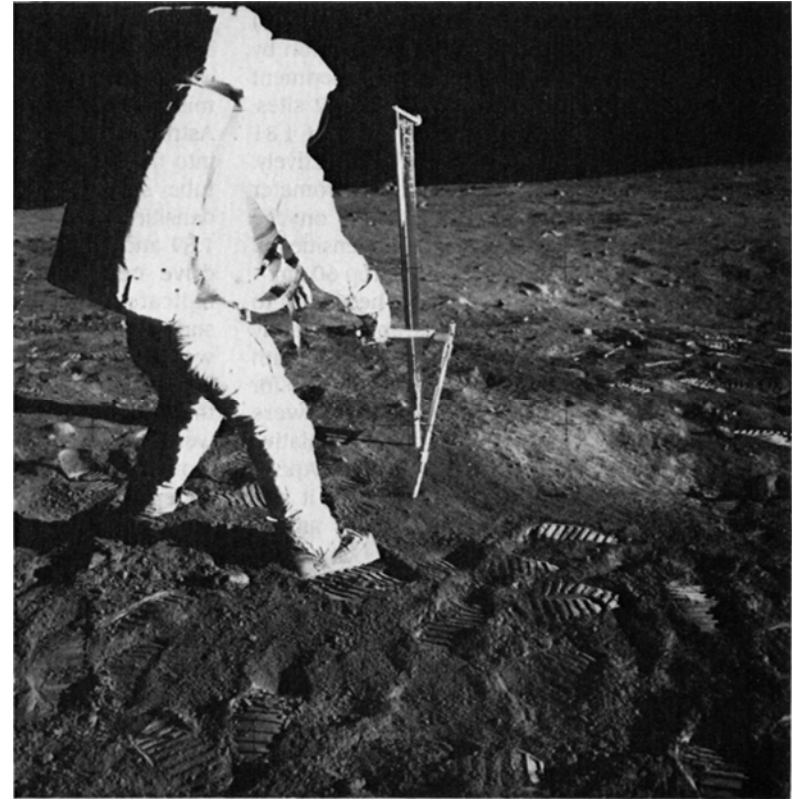
**No element test!?**



# Lunar exploration

**Mechanical properties  
of Lunar soil is needed.**

**But only TWO TC test  
results is available.**



Lunar regolith:  
very angular  
well graded sand

# Why granular mechanics?

---

**\*TRUE prediction**  
**from particle information**

eg.

**Mechanics of crushable soil**

**Mechanics of unsaturated soil**

**Mechanics of cemented soil**

**and more...**

**\*UNIQUE constitutive model**  
**more convincing, more rational**

# **Contents:**

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## **1. Theory of granular mechanics**

**Chang and Misra 1990, Matsushima and Chang 2006**

---

## **2. Micro X-ray CT experiment**

**Matsushima et al. 2002-**

---

## **3. Image-based DEM simulation**

**Matsushima 2002-**

---

**incl. recent application to Lunar exploration**

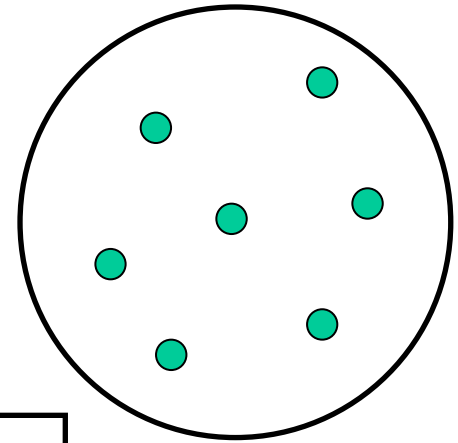
**Matsushima 2006**



# Basic theories

Molecular dynamics

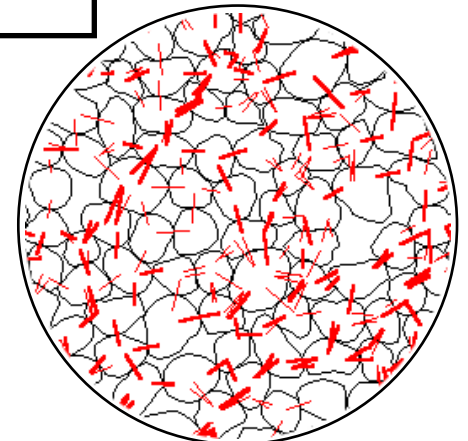
**Statistical mechanics** for molecules  
(sparse, non-frictional )



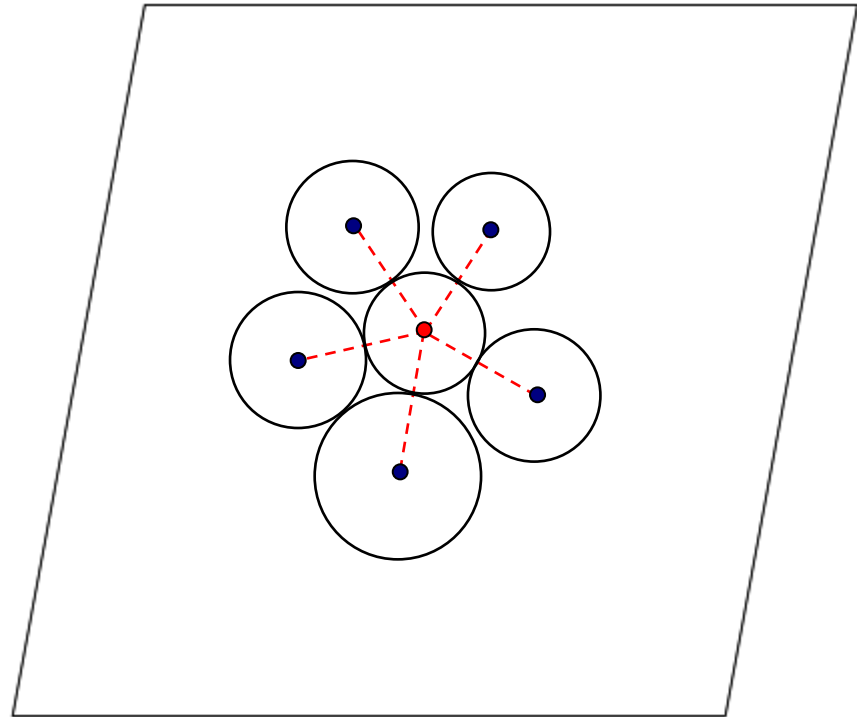
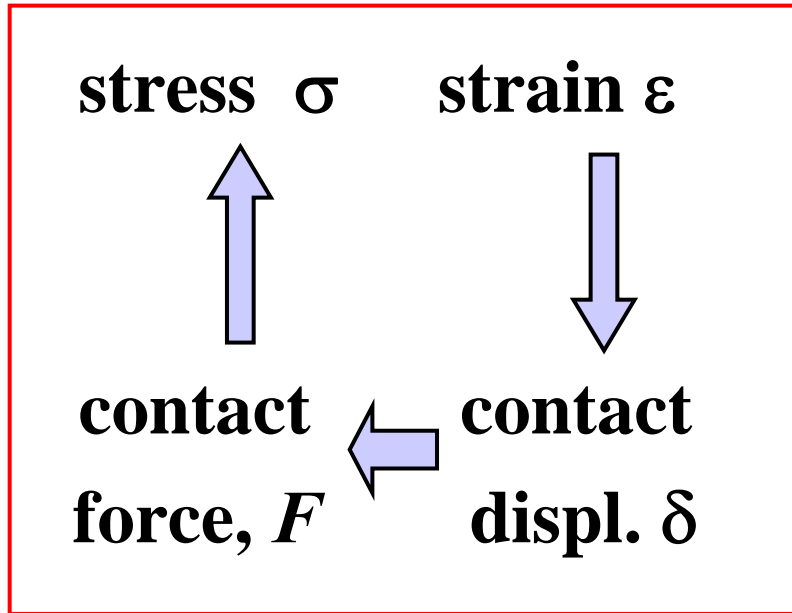
Mechanics of solid **frictional** particles  
Kinetic theory  
(sparse → behaves as a **fluid**)

+

Mechanics of **geomaterials**  
(dense → behaves as a **solid**)



# Uniform strain model (Chang and Misra 1990)



\*Grain centroids stick to continuum deformation field

\*Grain rotation coincides with continuum rotation

→ contact displ.  $\delta$



# Contact displ. → Contact force → Stress

Global → local coordinates

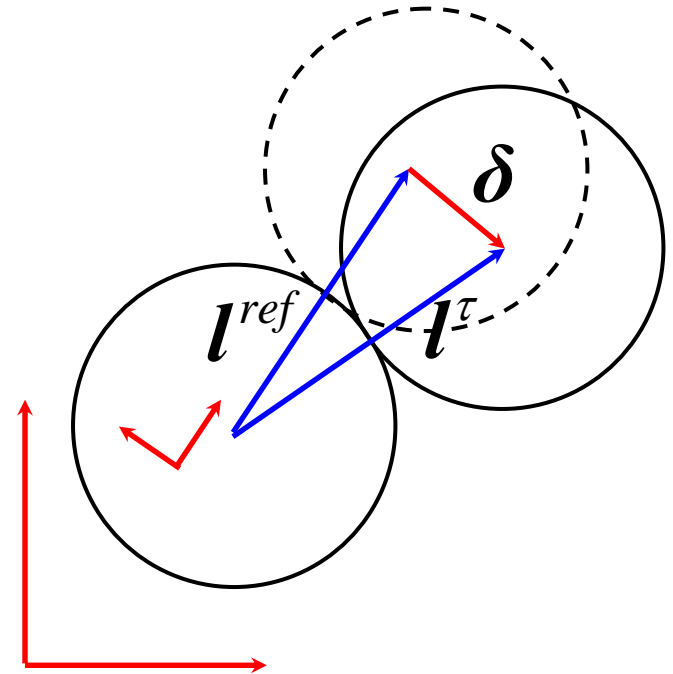
$$\delta^L = \mathbf{R}^T \cdot \delta$$

Force-displ. relation at contact

$$\mathbf{f}^L = \begin{pmatrix} f_n \\ f_s \end{pmatrix} = \begin{pmatrix} k_n & 0 \\ 0 & k_s \end{pmatrix} \cdot \delta^L$$

Global local coordinates

$$\mathbf{f} = \mathbf{R} \cdot \mathbf{f}^L$$



Stress

Sum of contacts in VR

$$\boldsymbol{\sigma}^{tT} = \frac{1}{V_R^t} \sum_c (\mathbf{l}^t \otimes \mathbf{f}^t)$$

work at contact = work as continuum



# Elastic solution

Assuming

equal-sized isotropic sphere packing...

$$\bar{E} = \frac{2r^2 N}{15V} (2k_n + 3k_s) \left( \frac{5k_n}{4k_n + k_s} \right)$$

$$\bar{\nu} = \frac{k_n - k_s}{4k_n + k_s}$$

*e-n* relation is necessary

$$\frac{N}{V} = \frac{3n}{4\pi r^3 (1 + e)}$$

*n* : coordination number

Overall Young's modulus and Poisson ratio  
can be described by contact stiffness



# Elastic solution (continued..)

Applying Hertz-Mindlin contact law... (Johnson, Contact mechanics)

$$\dot{f}_n = \left( \frac{\sqrt{3r} G}{1-\nu} \right)^{2/3} f_n^{1/3} \dot{\delta}_n \equiv k_n \dot{\delta}_n \qquad \dot{f}_s = \frac{2(1-\nu)}{2-\nu} k_n \left( 1 - \frac{f_s}{f_n \tan \phi_\mu} \right)^{1/3} \dot{\delta}_s \equiv k_s \dot{\delta}_s$$



$$\bar{E} = \frac{2r^2(5-4\nu)}{3(5-3\nu)} (9\sigma_0)^{1/3} \left[ \frac{GN}{(1-\nu)V} \right]^{2/3}$$

$$\bar{\nu} = \frac{\nu}{2(5-3\nu)}$$

$$\bar{G} = \frac{\bar{E}}{2(1+\bar{\nu})} = A \cdot \left( \frac{n(e)}{1+e} \right)^{2/3} (\sigma_0)^{1/3}$$

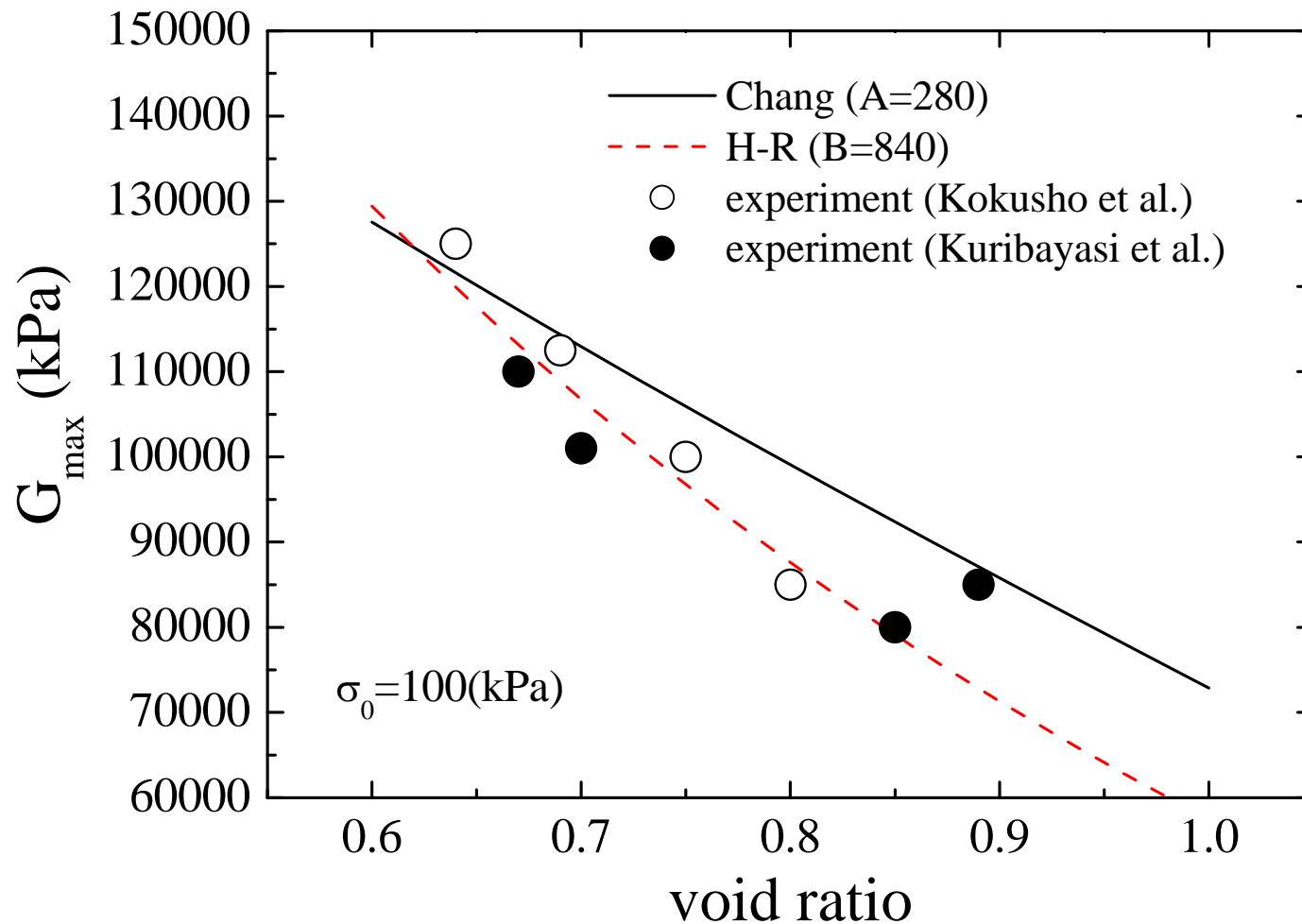
$$n(e) = 2.63 - 1.79e$$

$\bar{G}$  is a function of  
confining pressure,  $\sigma_0$   
and void ratio,  $e$

$$A = \frac{2r^2(5-4\nu)}{15(2-\nu)} (9)^{1/3} \left[ \frac{3G}{4\pi r^3(1-\nu)} \right]^{2/3}$$

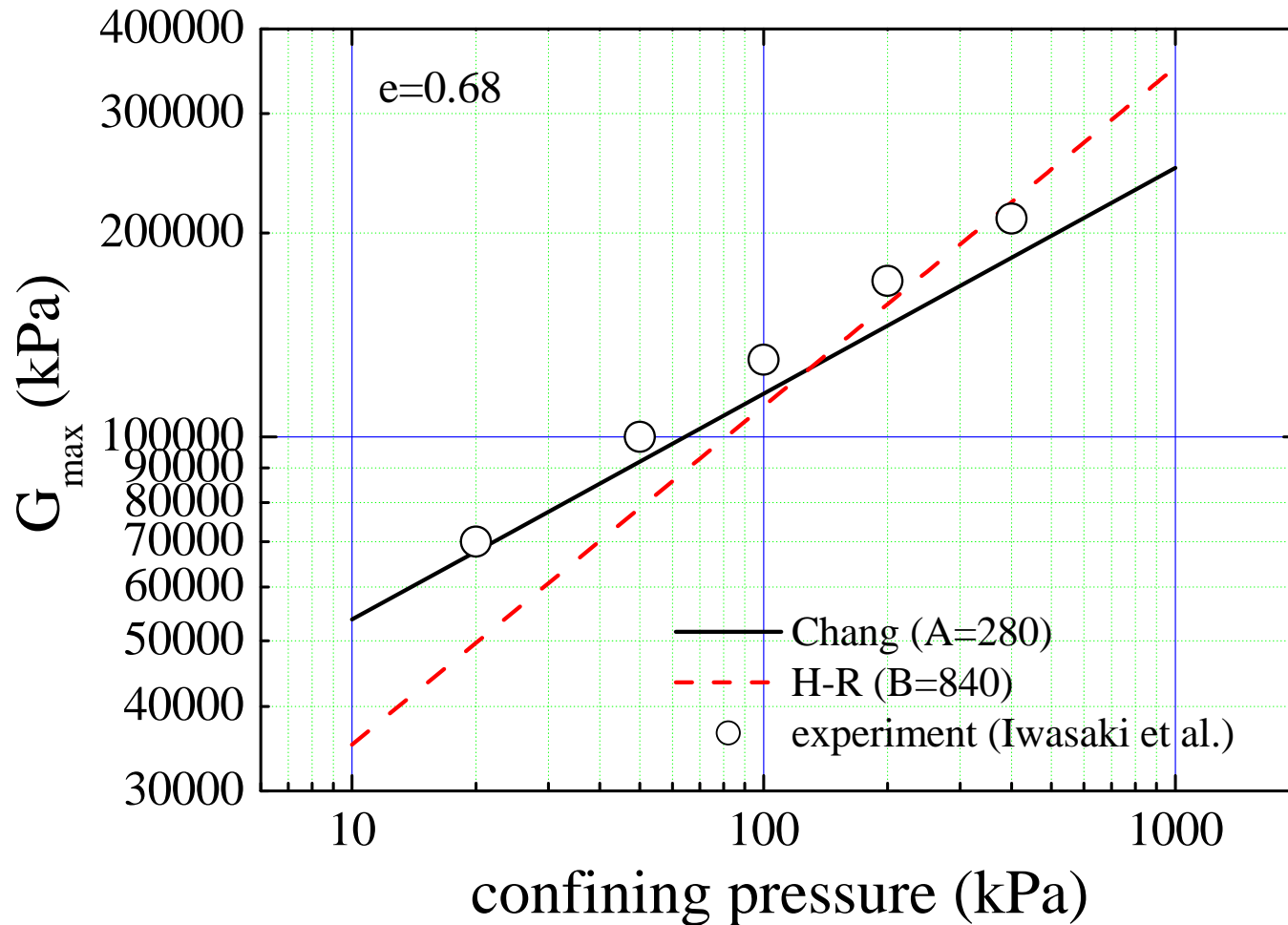
Smith et al. (1929) by the combination of closest and loosest packing 11

# Elastic solution (continued..)



Cf. Hardin & Richart 
$$\bar{G} = B \cdot \frac{(2.17 - e)^2}{1 + e} (\sigma_0)^{1/2}$$

# Elastic solution (continued..)



Cf. Hardin & Richart 
$$\bar{G} = B \cdot \frac{(2.17 - e)^2}{1 + e} (\sigma_0)^{1/2}$$



## Elastic solution (continued..)

---

*Note:*

$A=280$  corresponds to

$G=73(\text{GPa})$ ,  $\nu=0.25$  (sand particle as a solid)

Estimation of  $\bar{\nu}$  is not good.

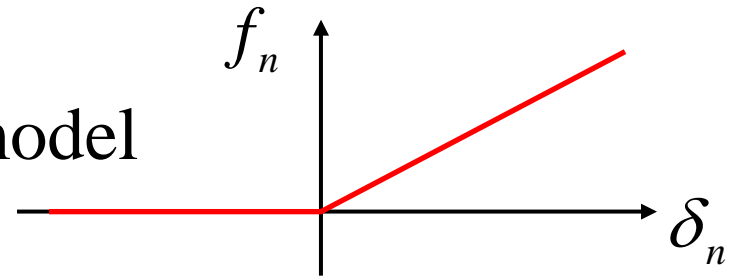
(Further research is necessary.)





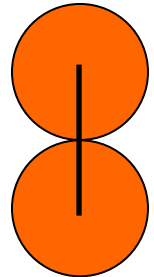
# Nonlinear model

- Loss of contact  
is considered by tension-free model



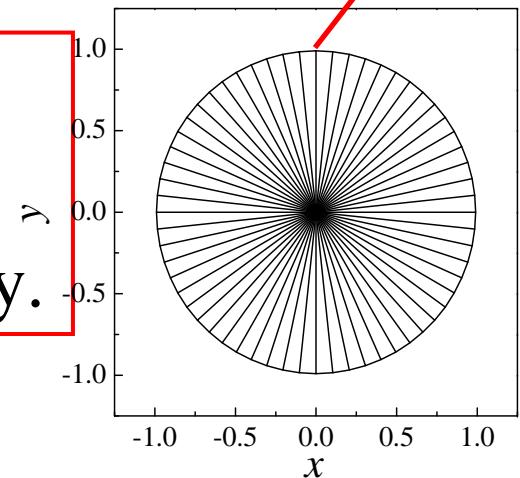
- Contact slip (plasticity)

$$|f_s| \begin{cases} \leq -\mu f_n & \rightarrow (\text{elastic}) \\ > -\mu f_n & \rightarrow (\text{sliding}) \end{cases} \rightarrow |f_s| = -\mu f_n \text{sign}(f_s)$$

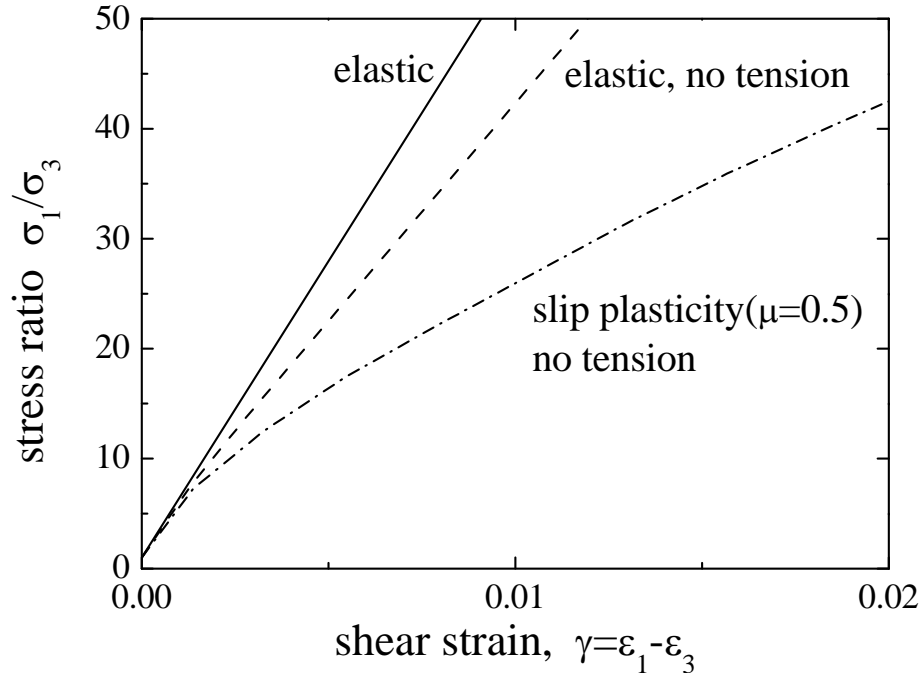


Analytical solution is not available.

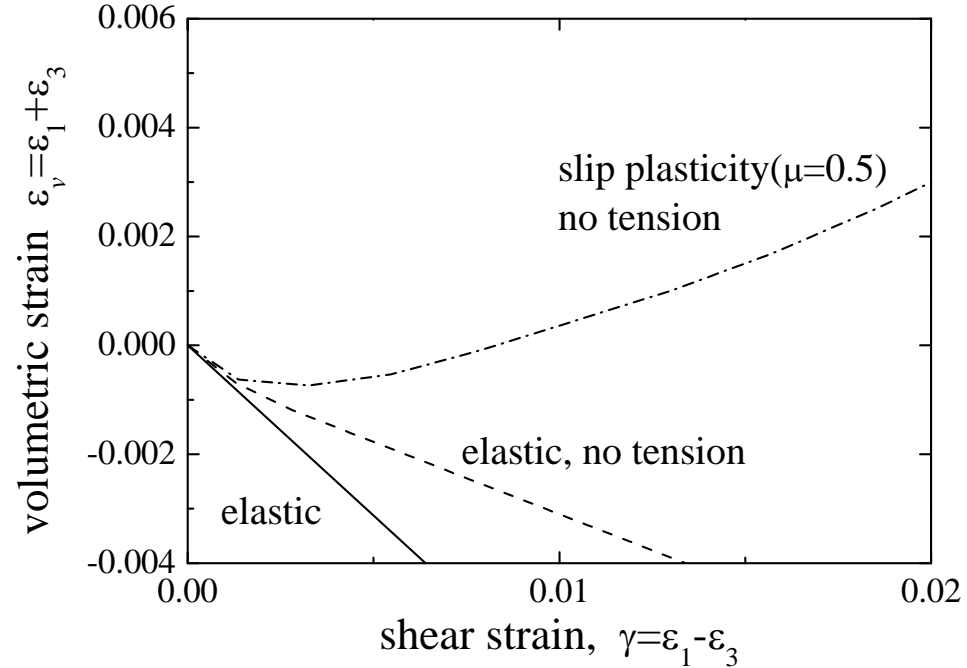
→ A set of branch vectors are assumed and the solution is obtained numerically.



# Basic response (biaxial compression)



stress-strain curve



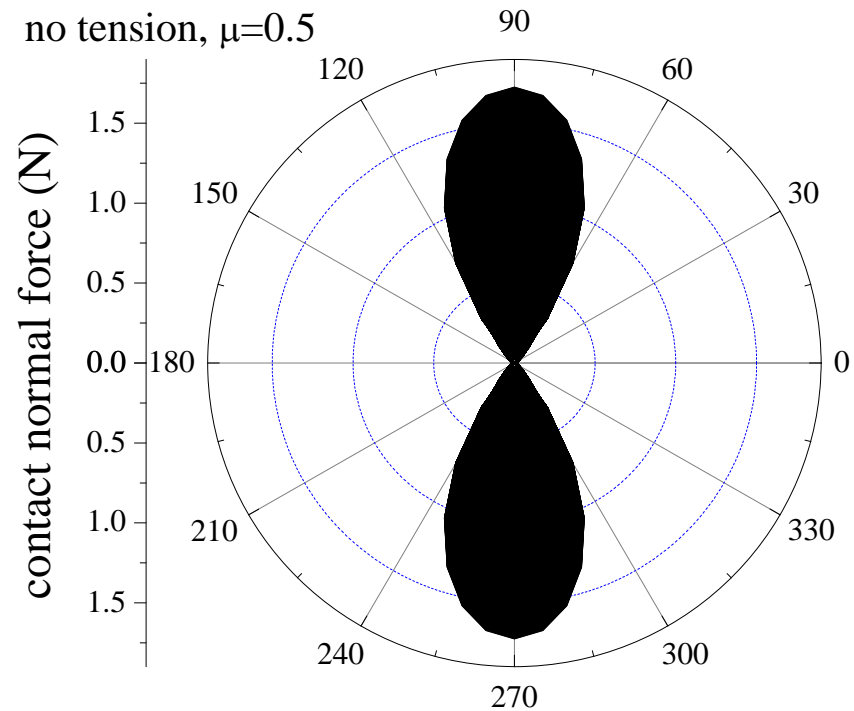
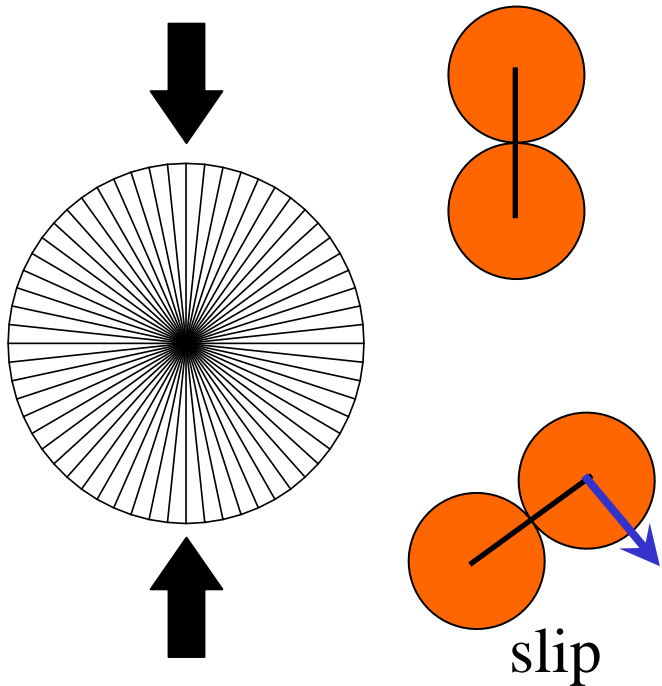
dilation curve

**Material does NOT yield!**

# Basic response (biaxial compression)

Why?

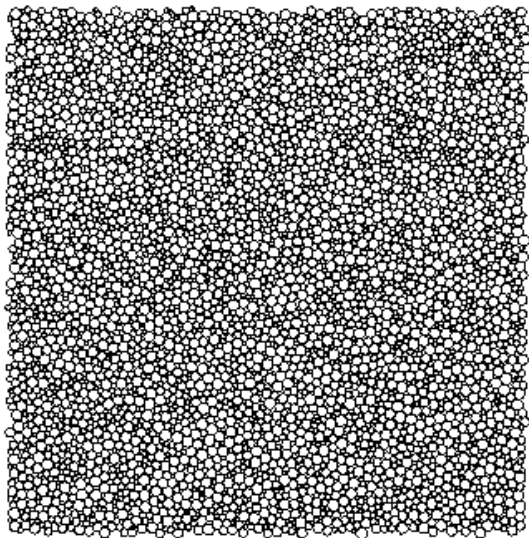
Contact of loading direction does NOT slip.



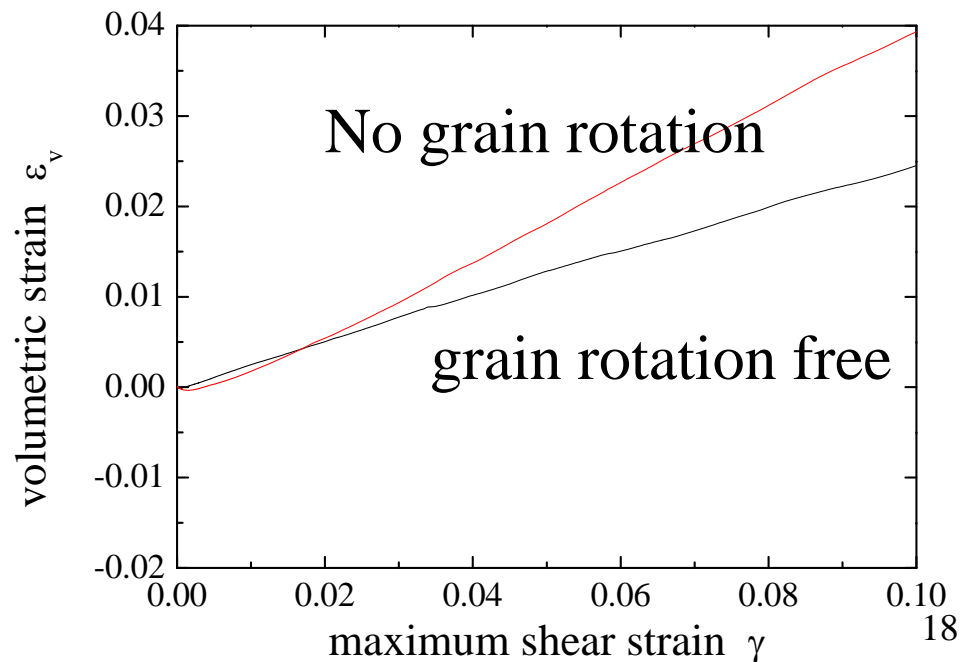
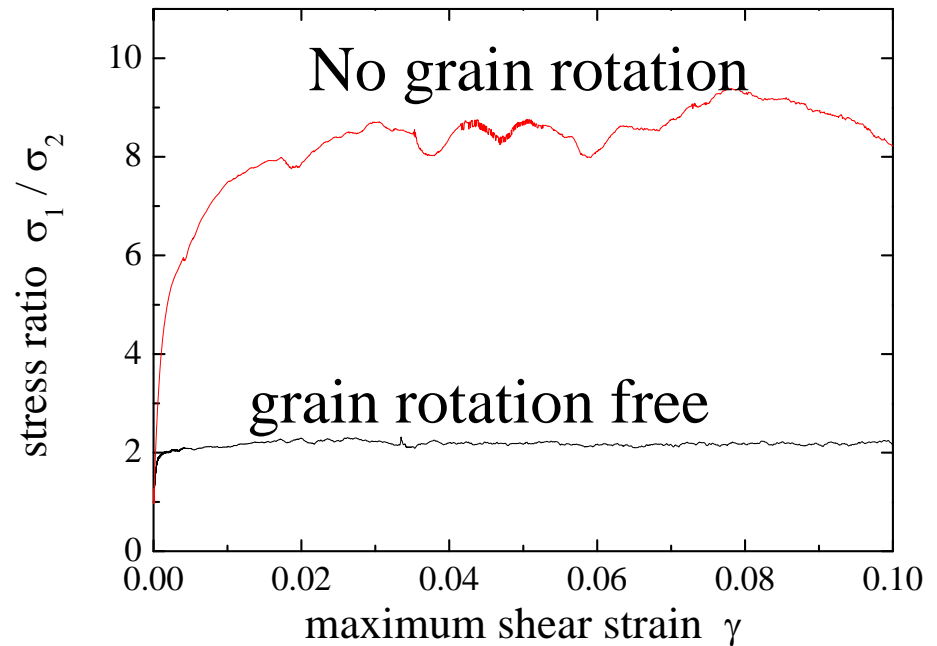
Contact normal force distribution



# DEM study

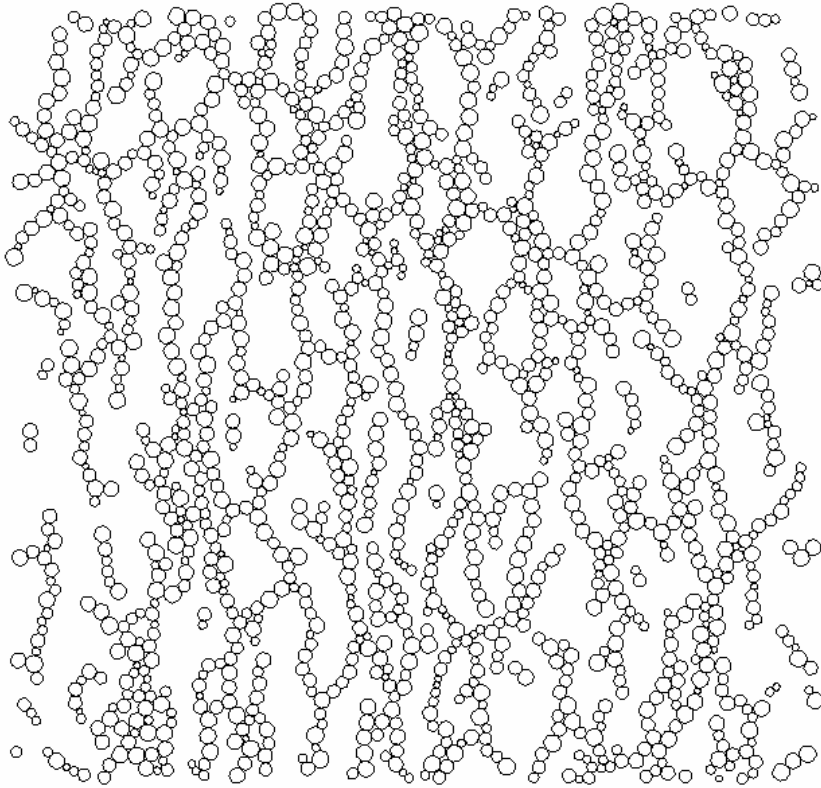


periodic boundaries  
at both directions

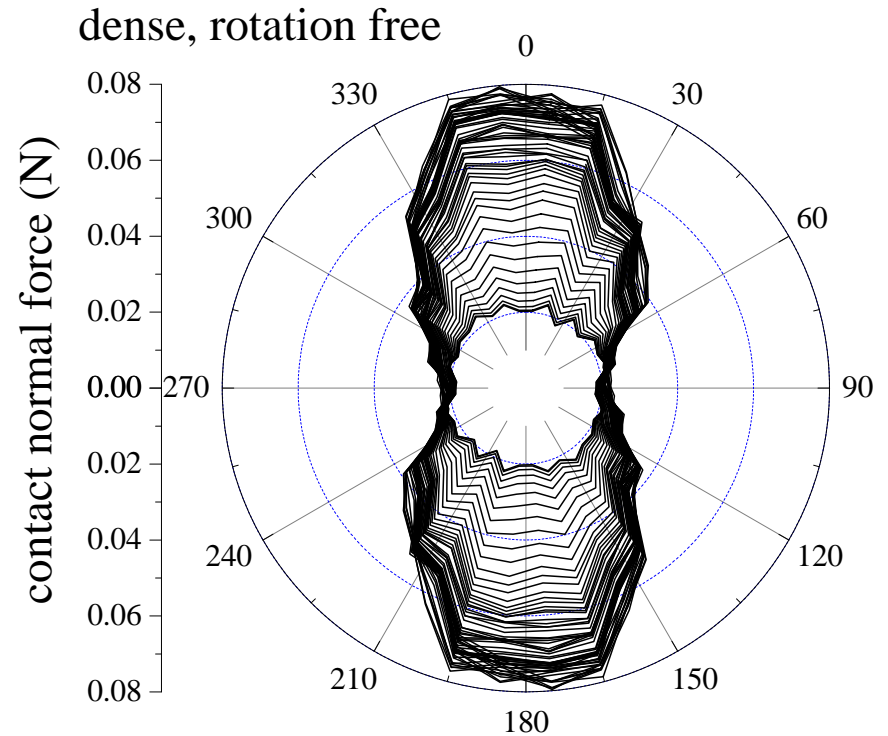




# DEM study

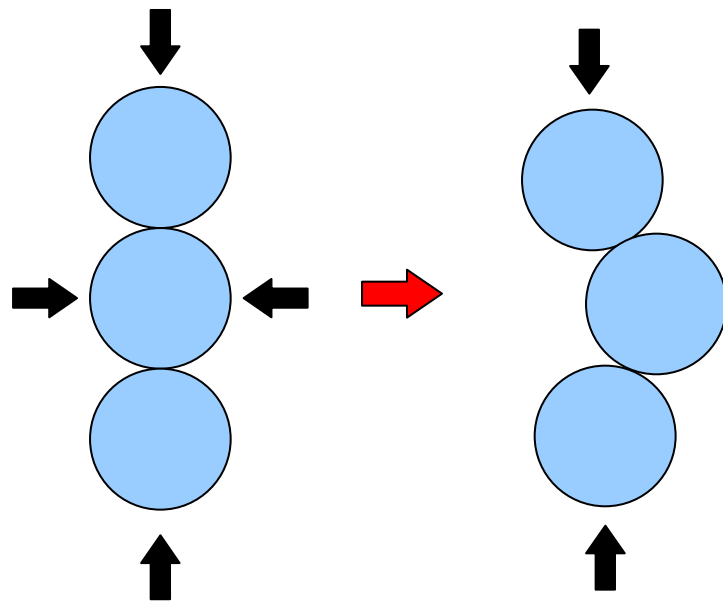


Force chain  
in granular assembly



Contact normal force  
distribution

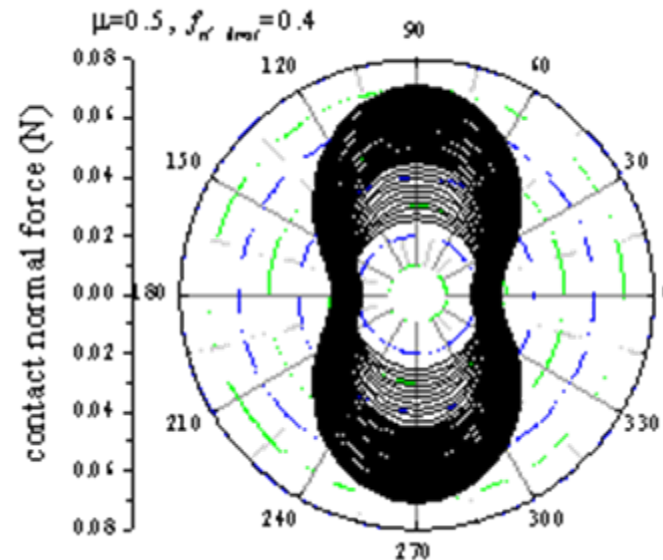
# Buckling of granular column



insufficient confining  
pressure  
↓  
buckling

(Matsushima and Chang, 2006)

- Assign minimum aspect ratio for contact force distribution
- Determine average contact force such that the stored energy in contact keeps constant

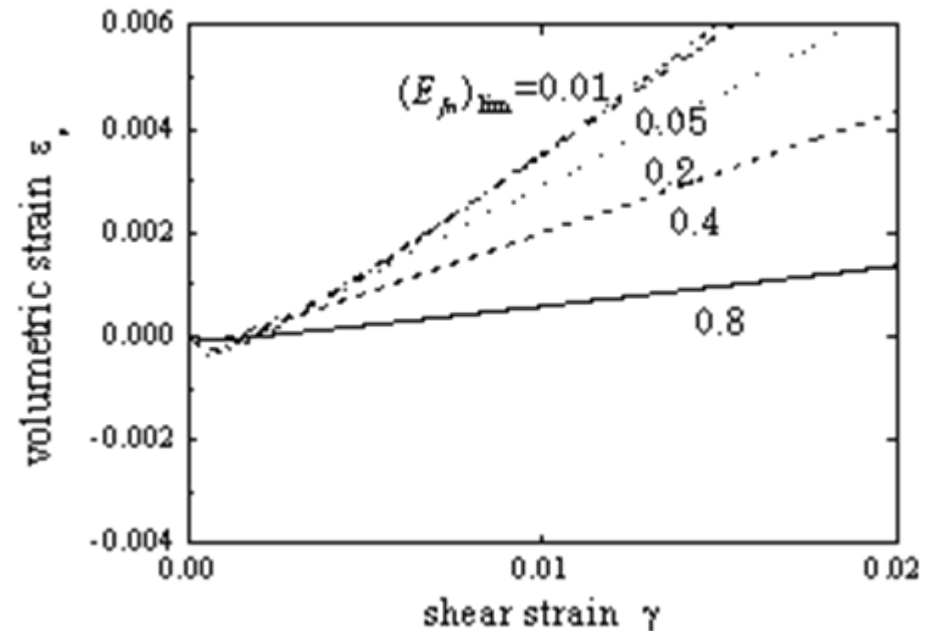
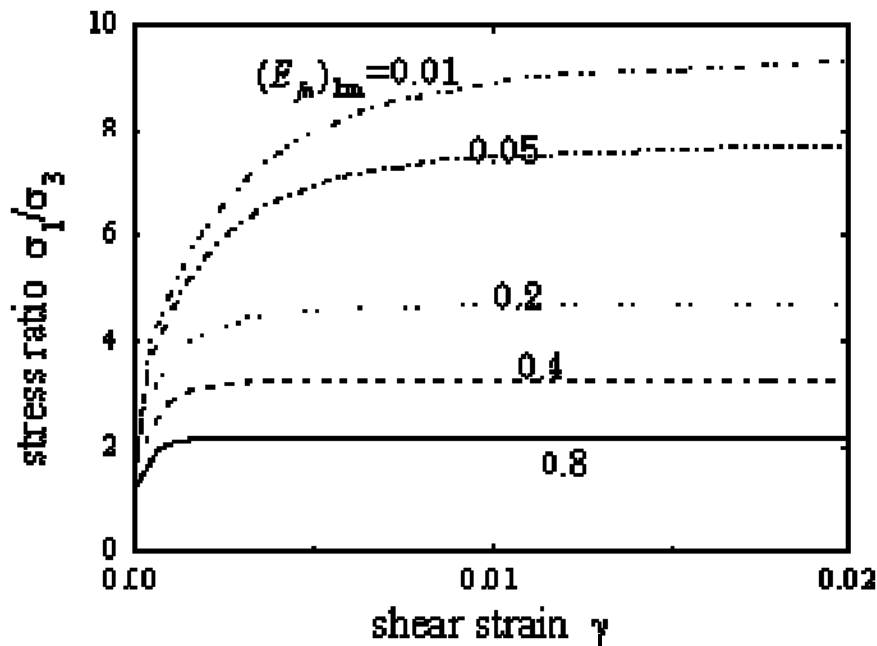






# Response of Buckling model

(Matsushima and Chang, 2006)



**Buckling resistance controls the yield strength**

related to particle properties

# Possibility of granular mechanics C.E.

Rational incorporation of particle properties  
(size, shape, stiffness, crushability, contact cement, etc.)

Validation not only with macro response  
but also with particle-level information

Detailed comparison with

**Particle visualization experiment**

**More realistic DEM**

is needed.

# Particle visualization by Micro X-ray CT

---



At University Joseph Fourier, Grenoble, 2002



# Objective

---

to obtain **3-D micro properties**  
(grain properties, microstructure  
and its change due to external loading)  
of some standard sands  
with **micro X-ray CT** in SPring-8

**Typical standard sands:**

**Toyoura sand:  $D_{50} = 0.167$ (mm)**

**Ottawa sand:  $D_{50} = 0.174$ (mm)**

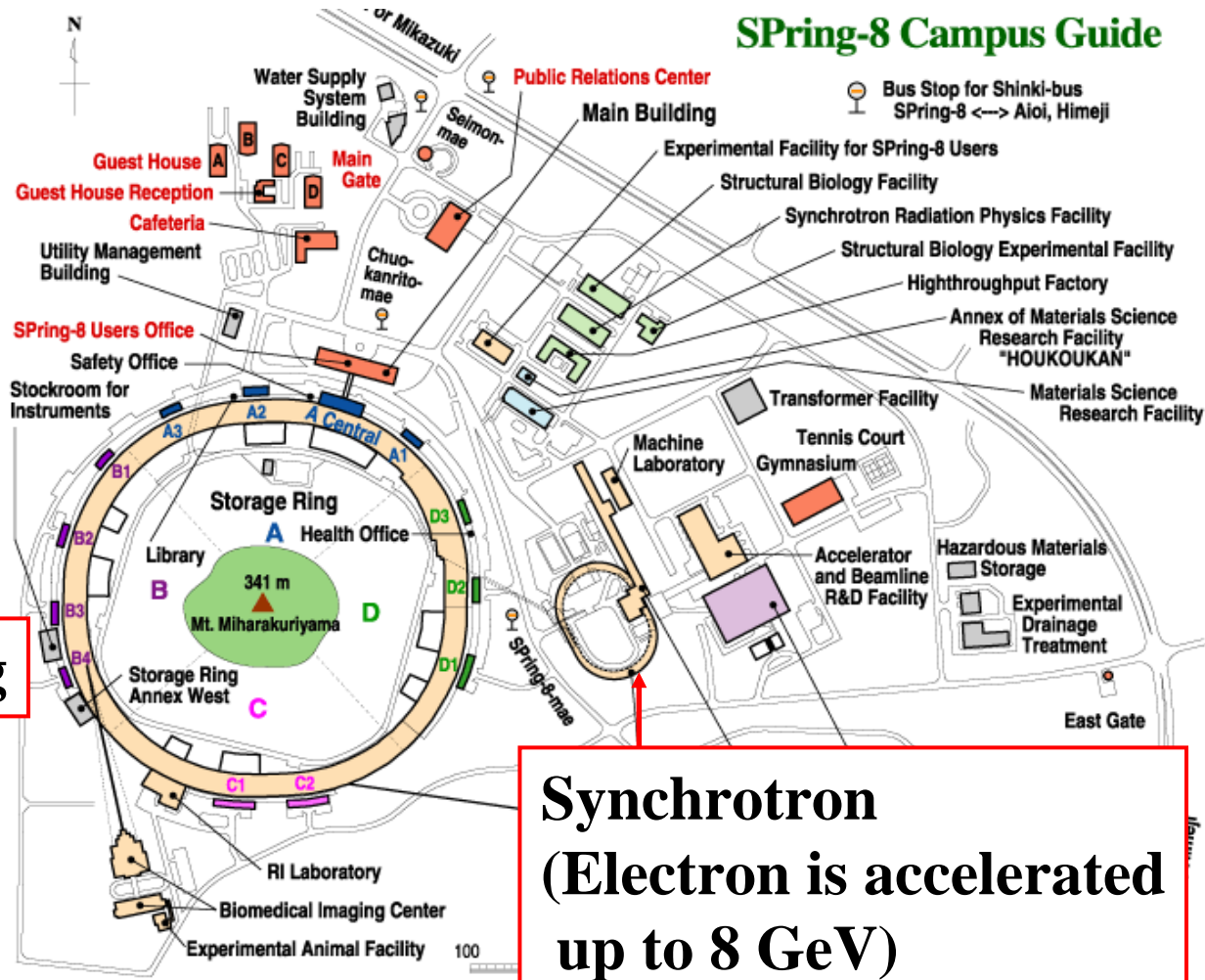
**Hostun sand:  $D_{50} = 0.408$ (mm)**

**S.L.B. sand:  $D_{50} = 0.681$ (mm)**

**(high resolution system is necessary)**

# Micro X-ray CT at Spring-8

## SPring-8 Campus Guide



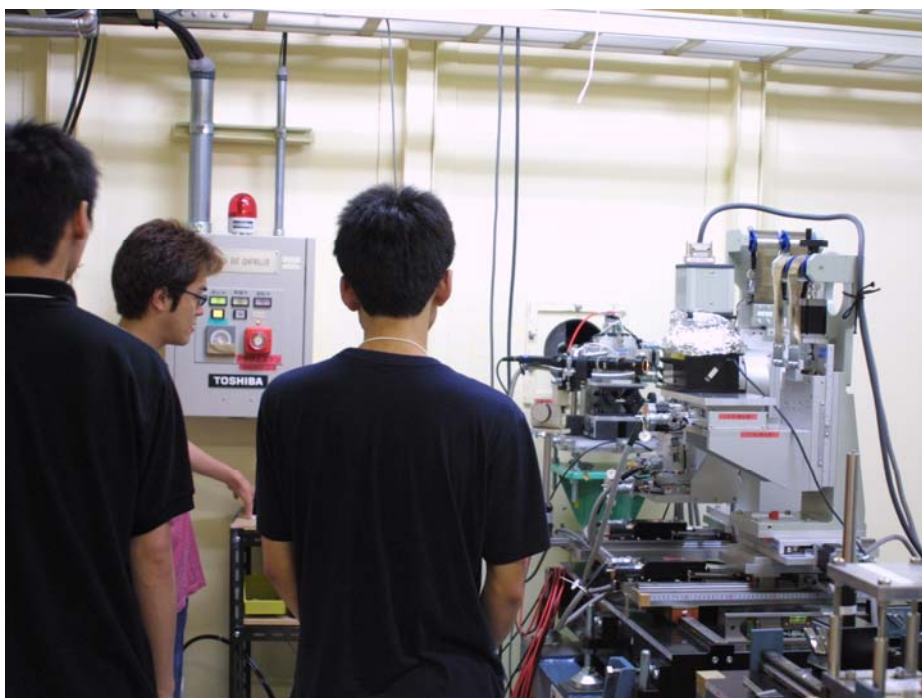
**The world's largest third-generation  
synchrotron radiation facility**



# Storage ring facility



# Experimental room



**47 beamlines (BL)**

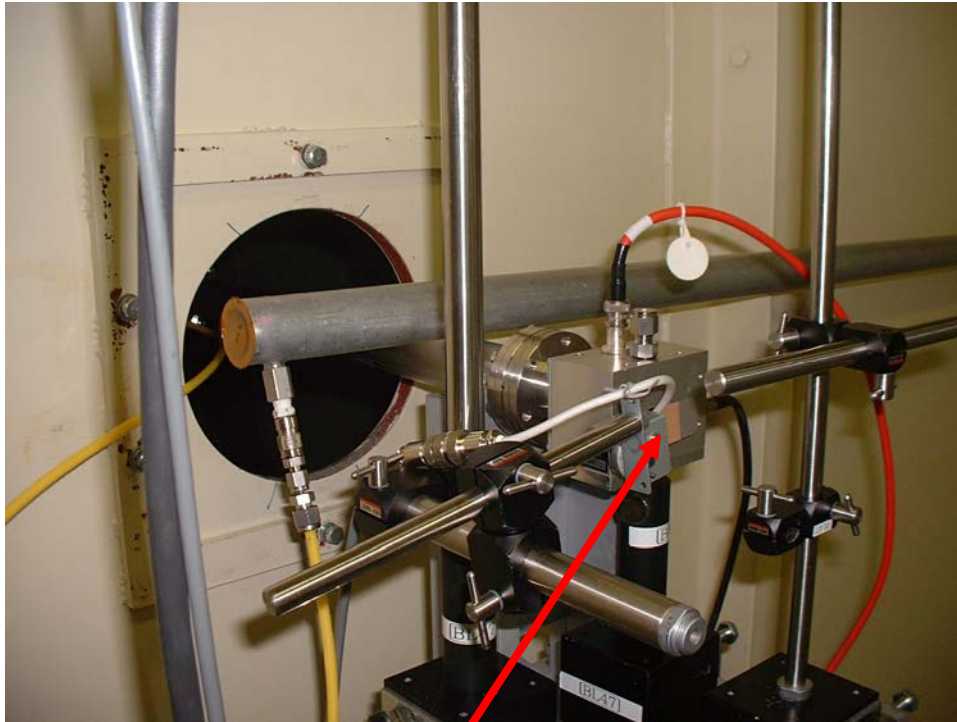
**X-ray CT is available at  
BL20B2 and BL47XU.**



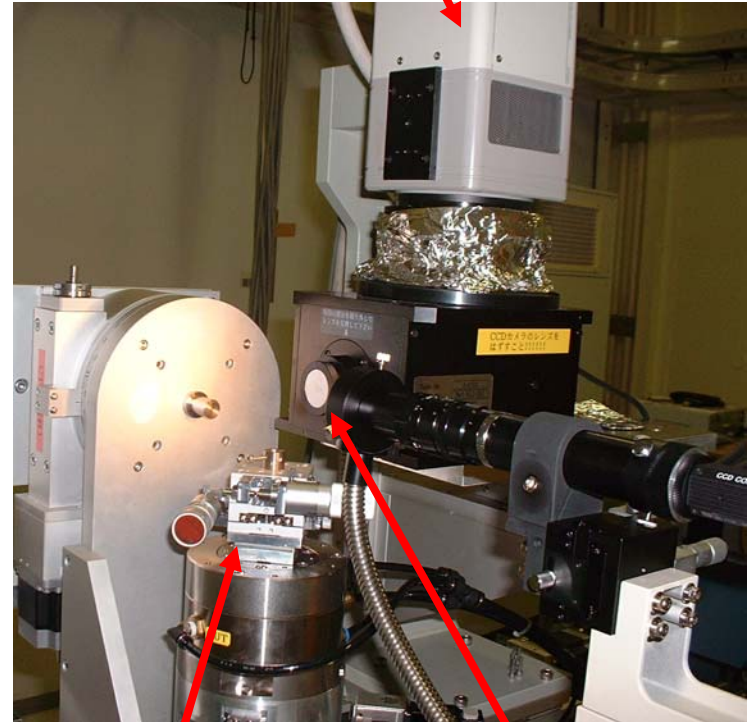


# Outline of Spring-8

CCD camera



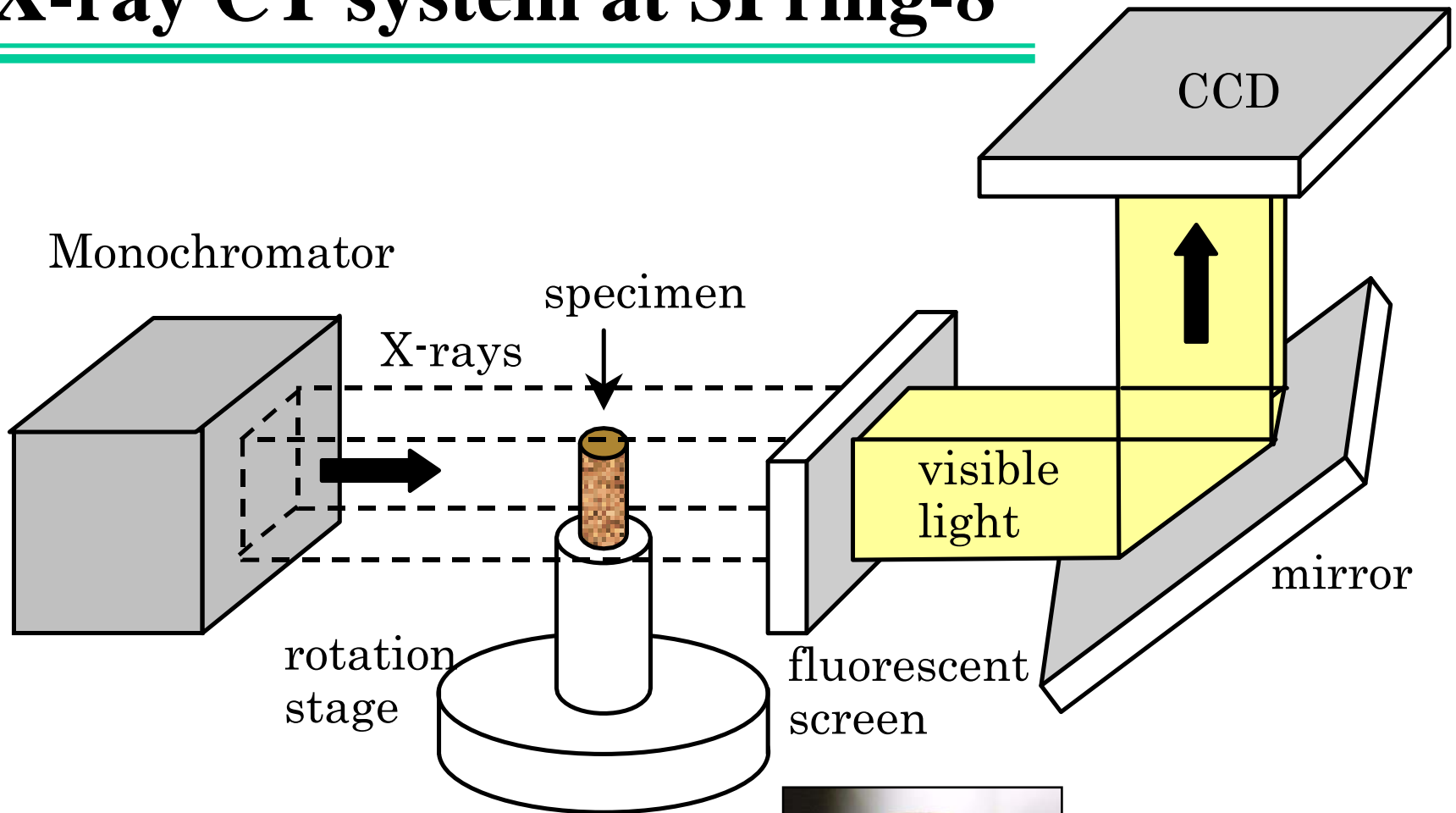
X-ray comes from here



Stage

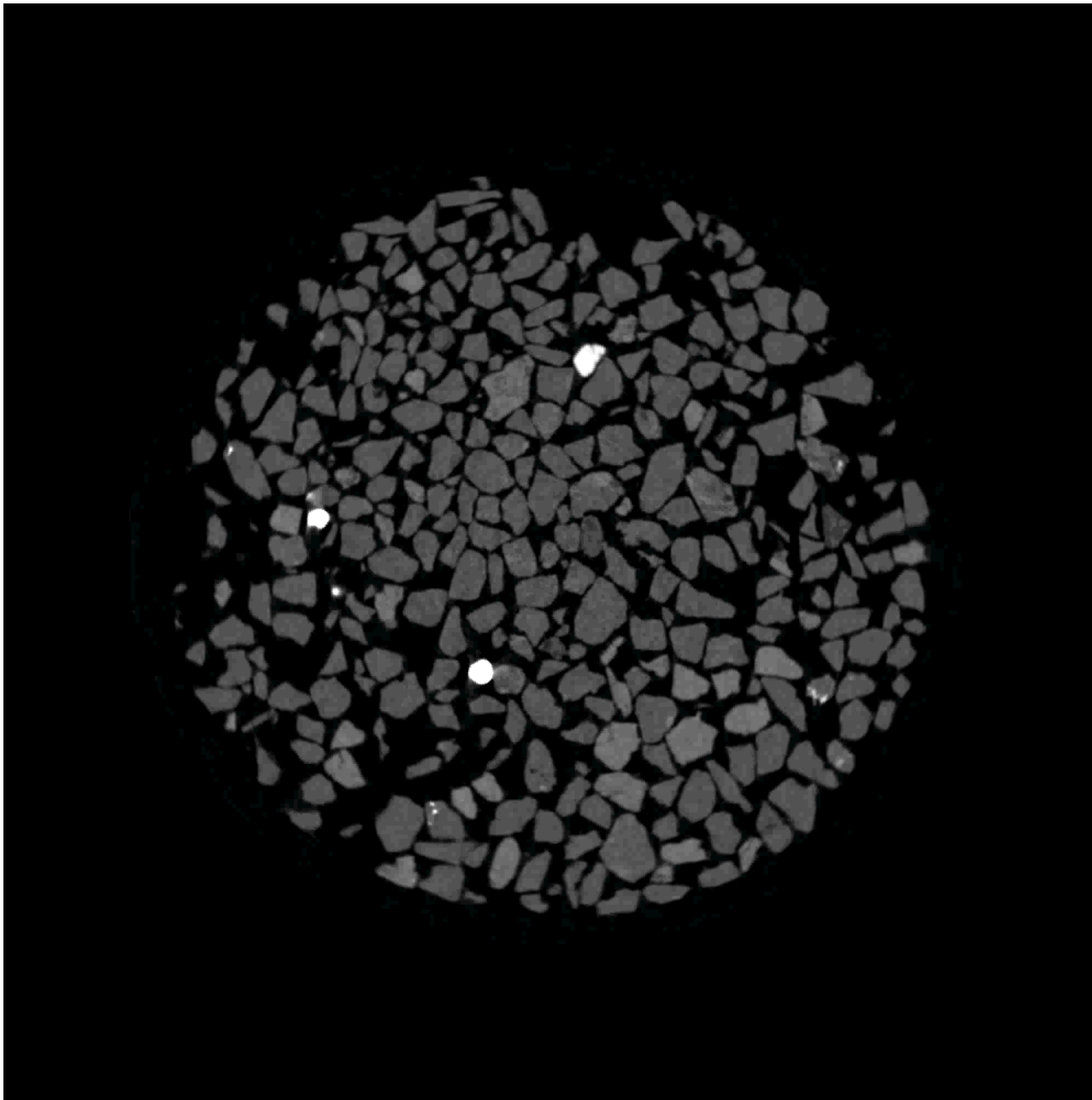
Detector

# X-ray CT system at SPring-8



**Resolution:**  
**BL20B2: 13  $\mu\text{m}$**   
**BL47XU: 1.5  $\mu\text{m}$**



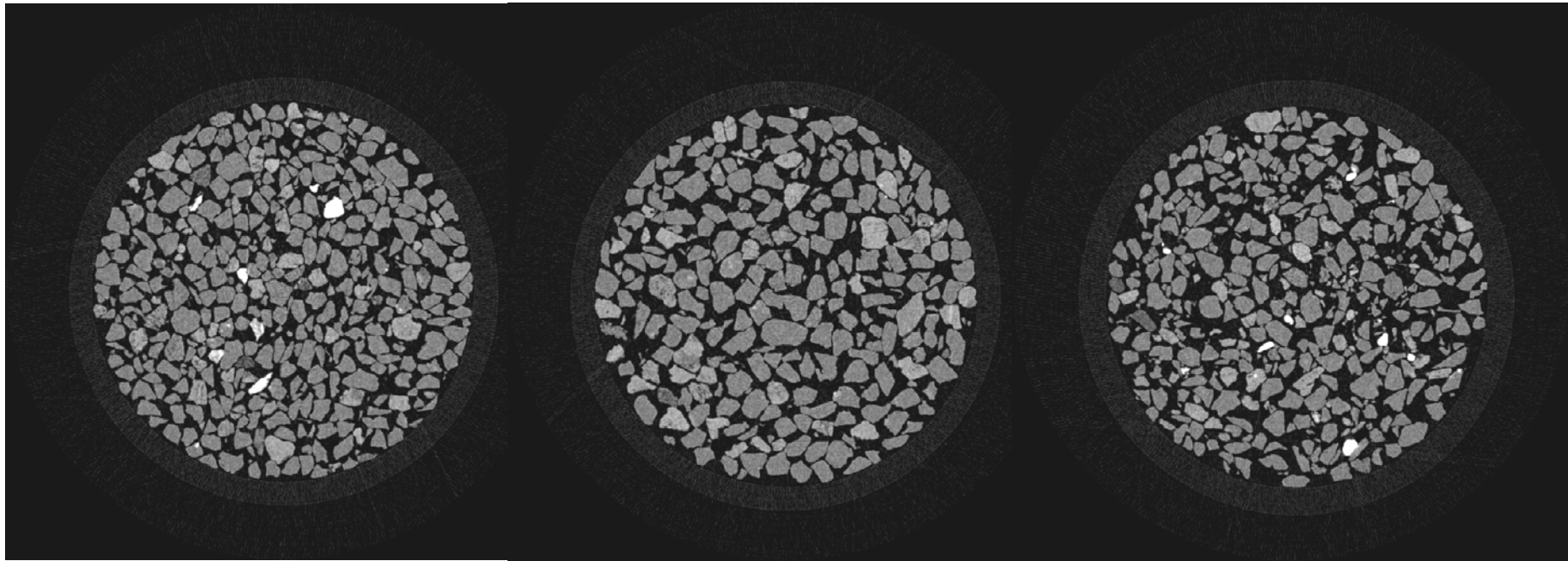


**Toyoura sand      dense**

# Example of CT image (BL20B2)

---

## Toyoura sand



**dense**

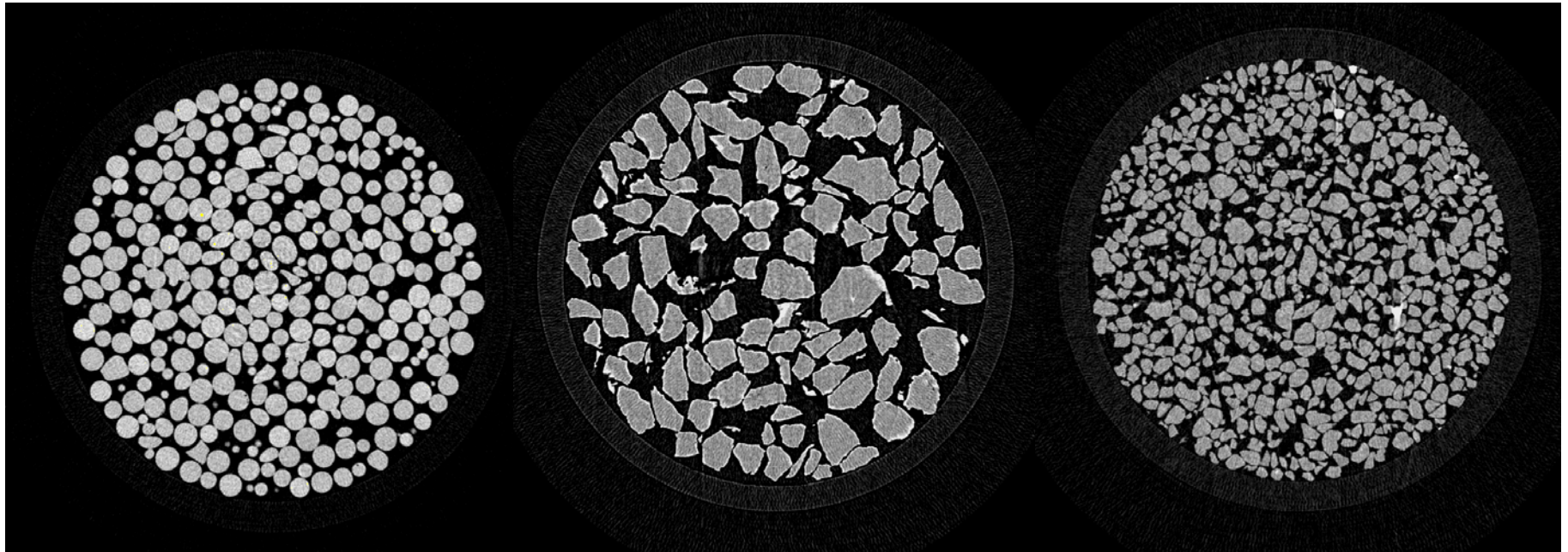
**medium dense**

**loose**



# Example of CT image (BL20B2)

---

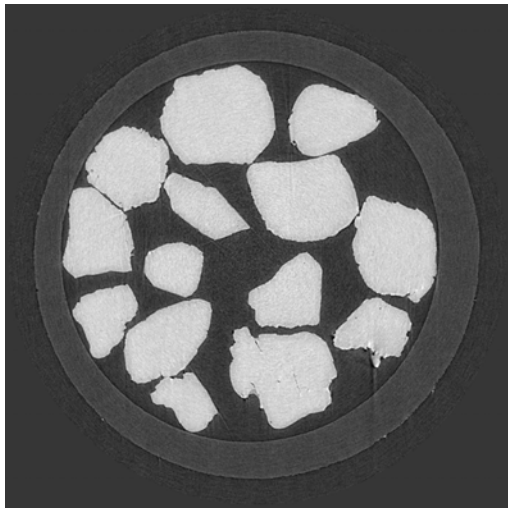


**Glass beads**

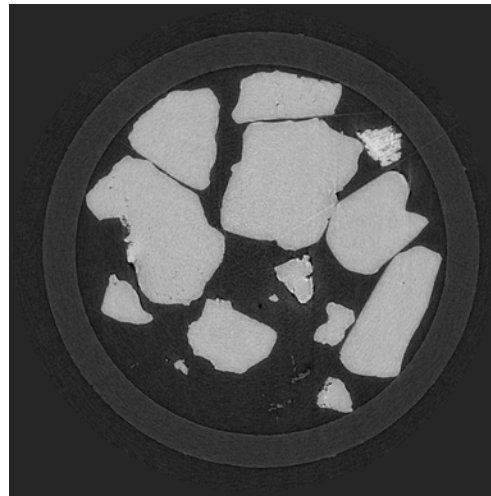
**Hostun sand**

**Ottawa sand**

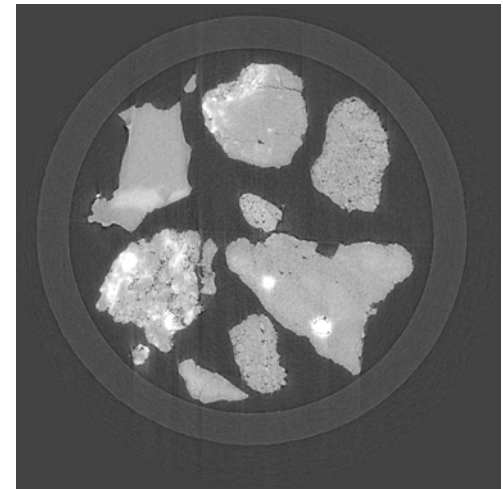
# Example of CT image (BL47XU)



**Ottawa sand**



**Toyoura sand**

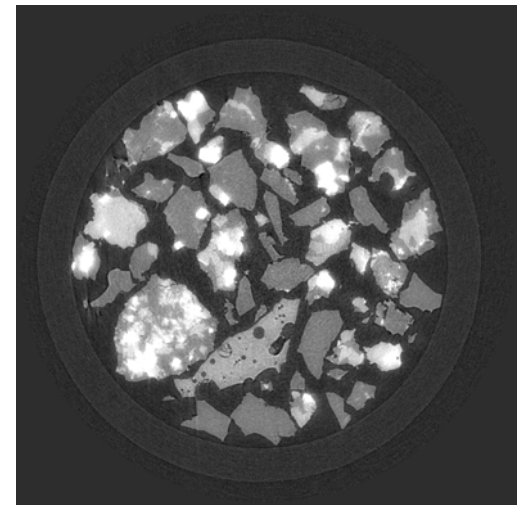


**Wakasa sand**

**Roundish**



**very angular**

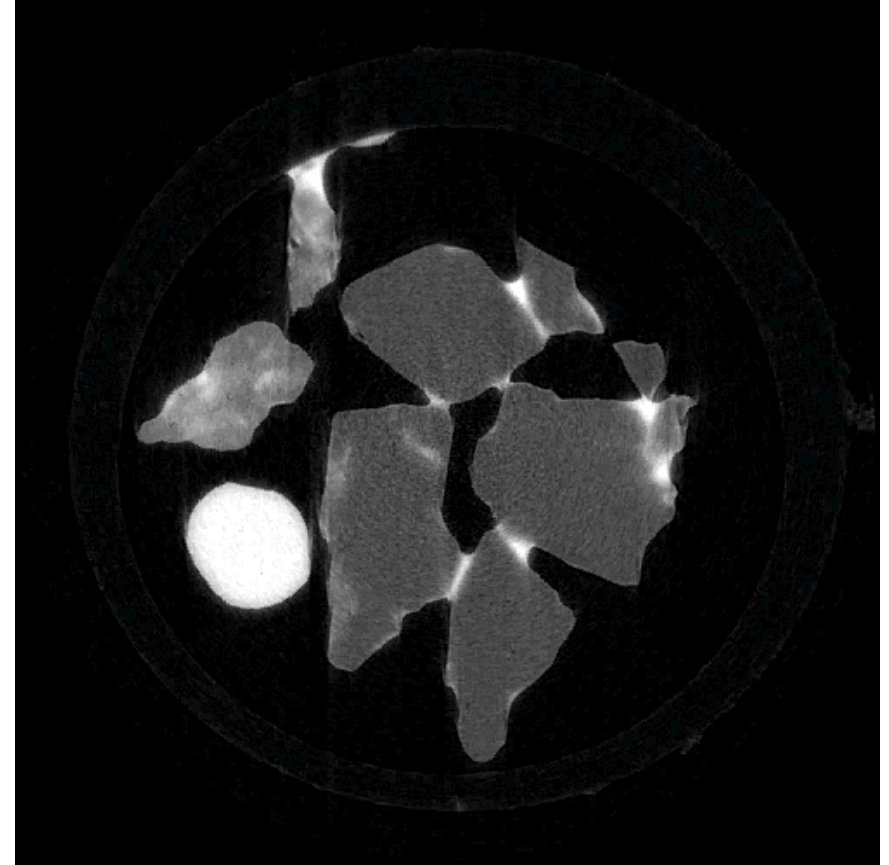


**Lunar soil simulant(FJS-1)<sub>32</sub>**

# Example of CT image (BL47XU)



**Masado (crushable sand)**

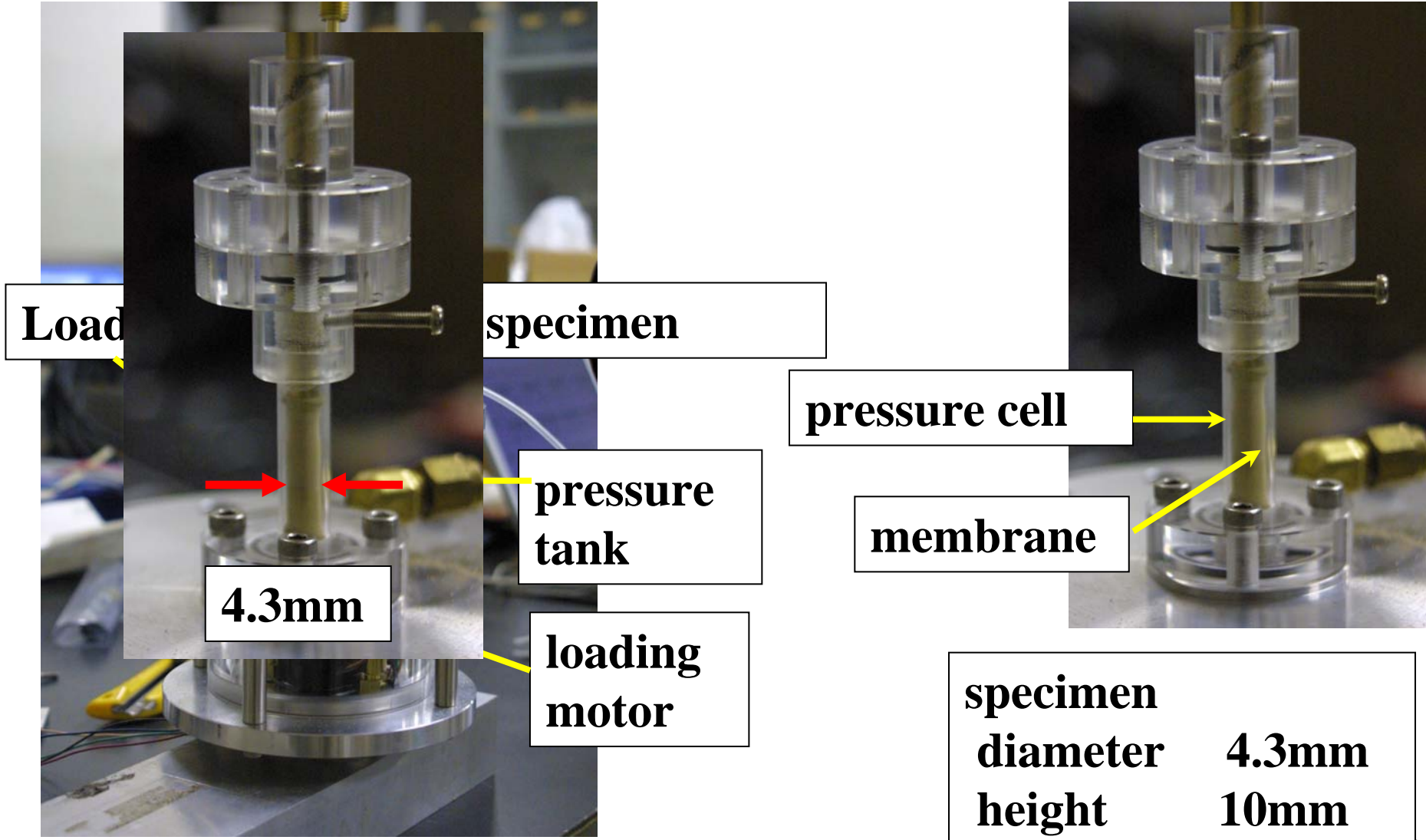


**unsaturated condition**



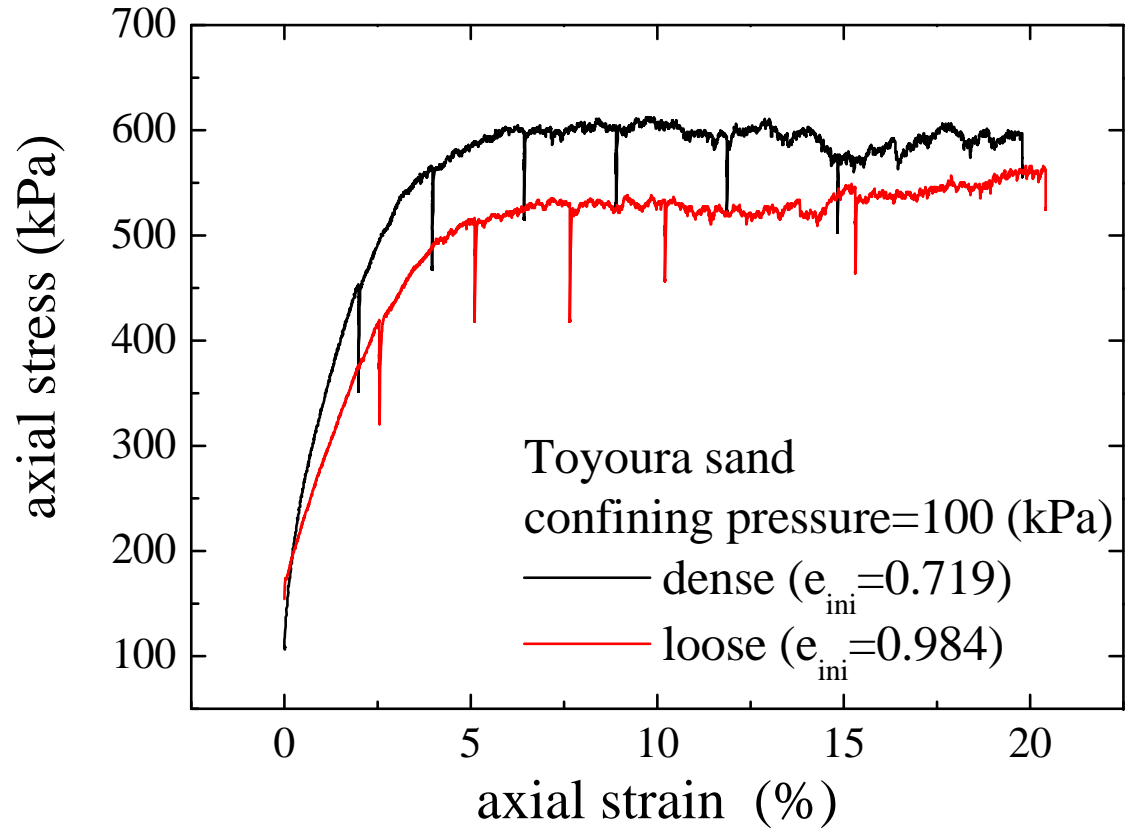
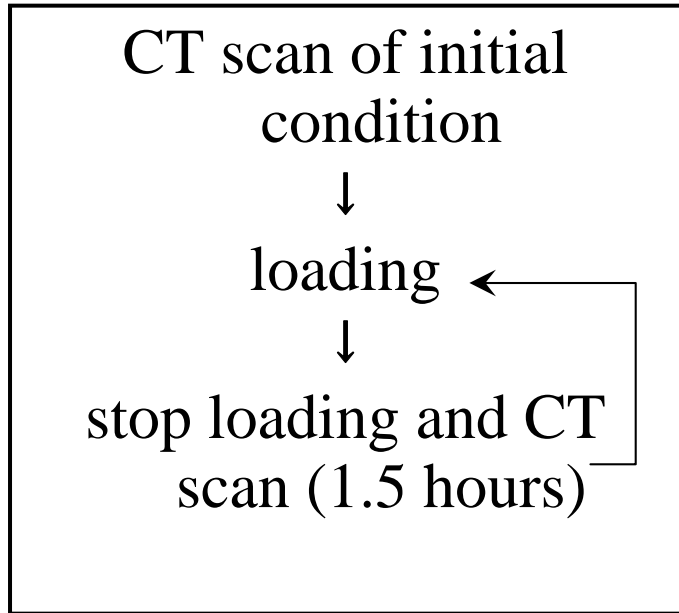


# Micro Triaxial test (BL20B2)(1)





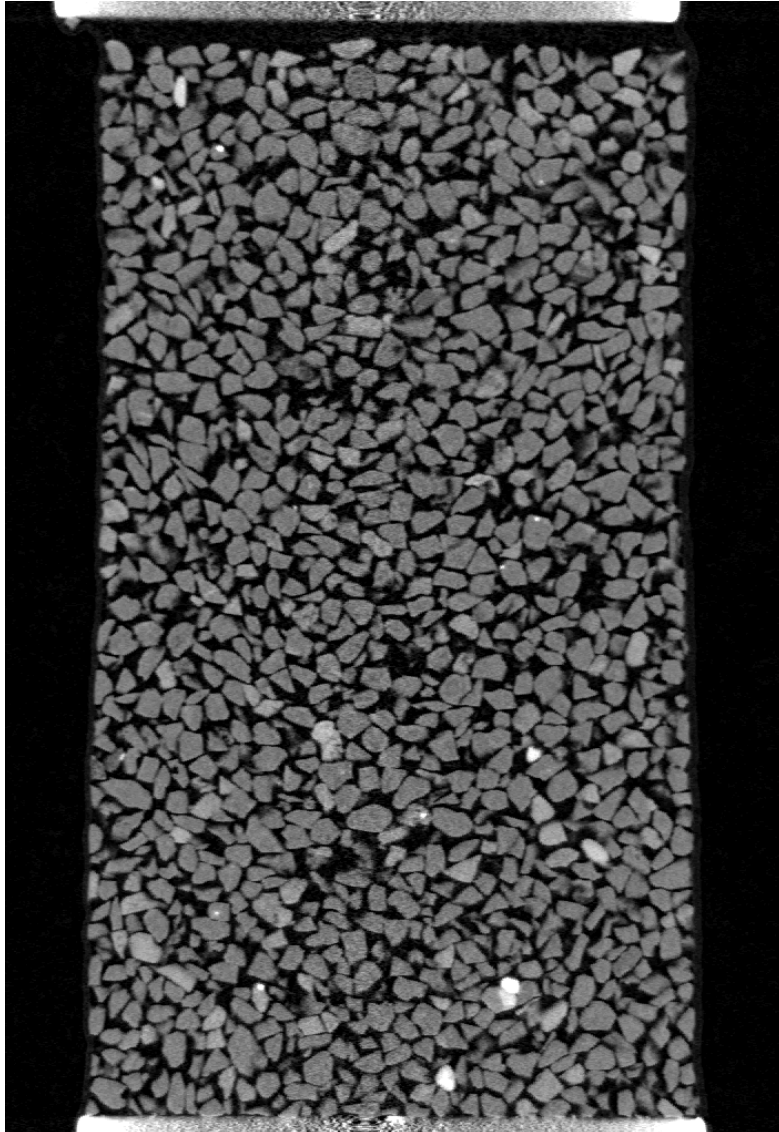
# Micro Triaxial test (BL20B2)(2)



stress-strain curve



# Micro Triaxial test (BL20B2)(3)



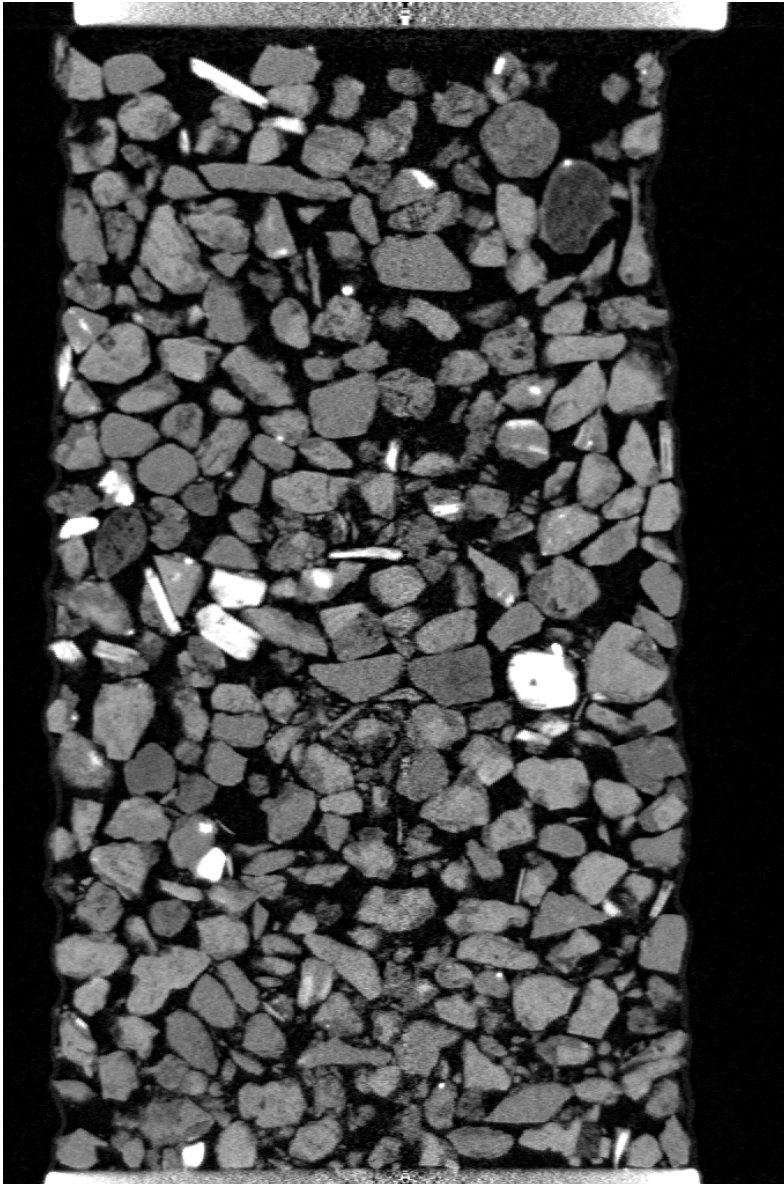
Toyoura  
(medium dense)

← void increase within  
a shear band



# Micro Triaxial test (BL20B2)(4)

---



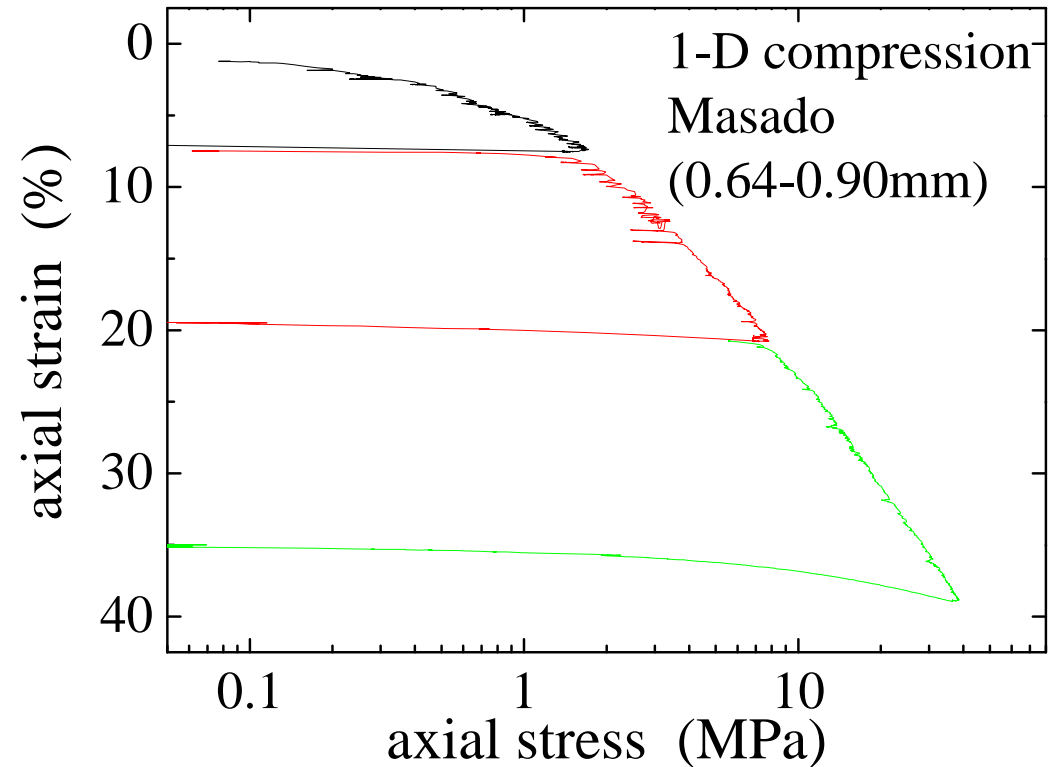
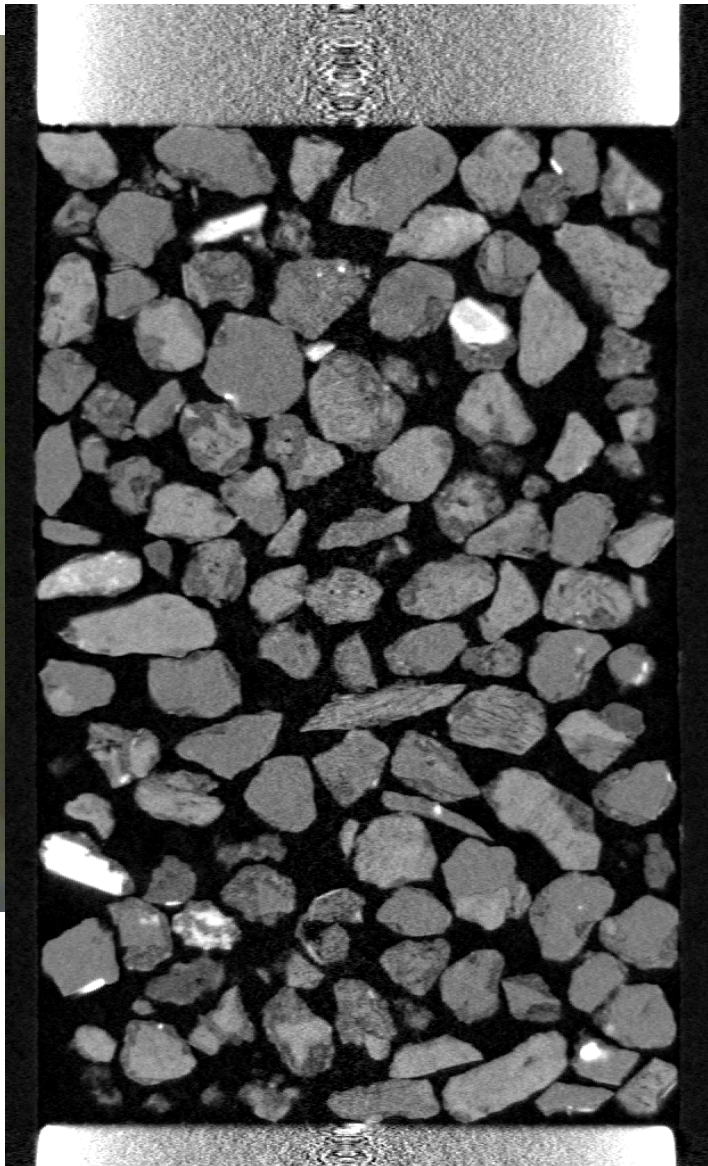
Masado (cruchable sand)  
0.351-0.64mm  
(medium dense)

particle crushing is  
NOT predominant





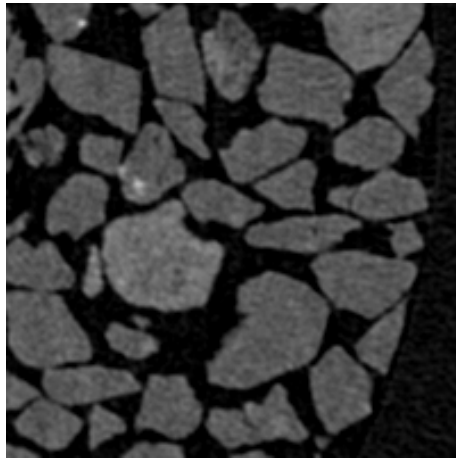
# Micro 1-D compression test



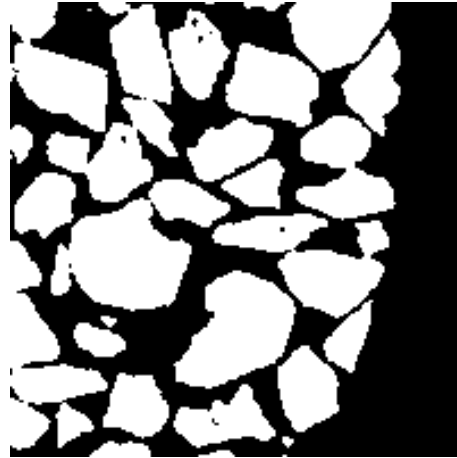
**particle crushing  
after yield stress**



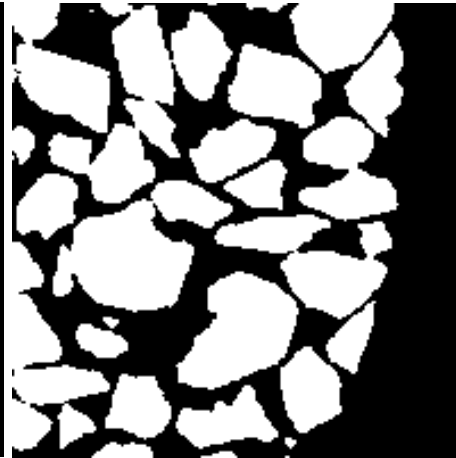
# Processing of CT image



Original image



After binarization



After pore-filling



After 1st erosion



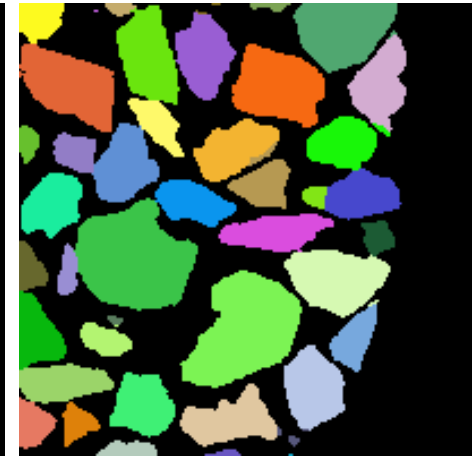
After 2nd erosion



After 3rd erosion



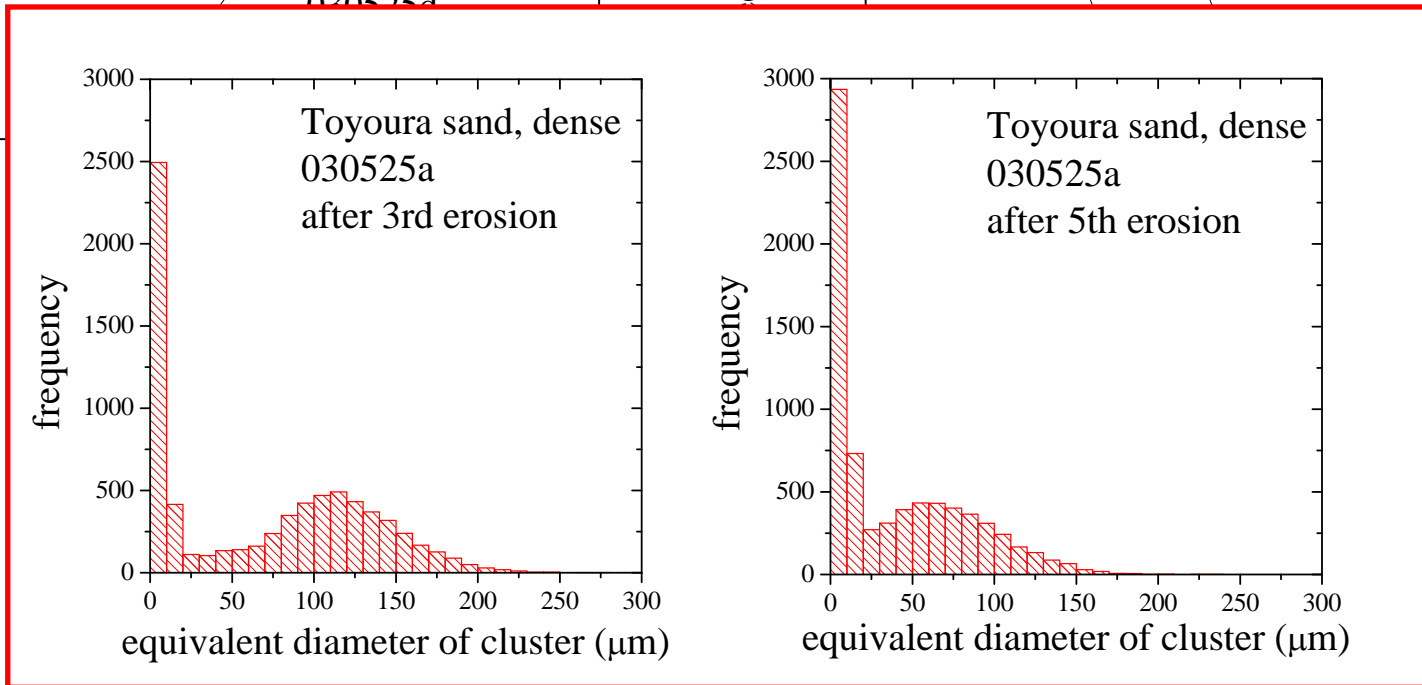
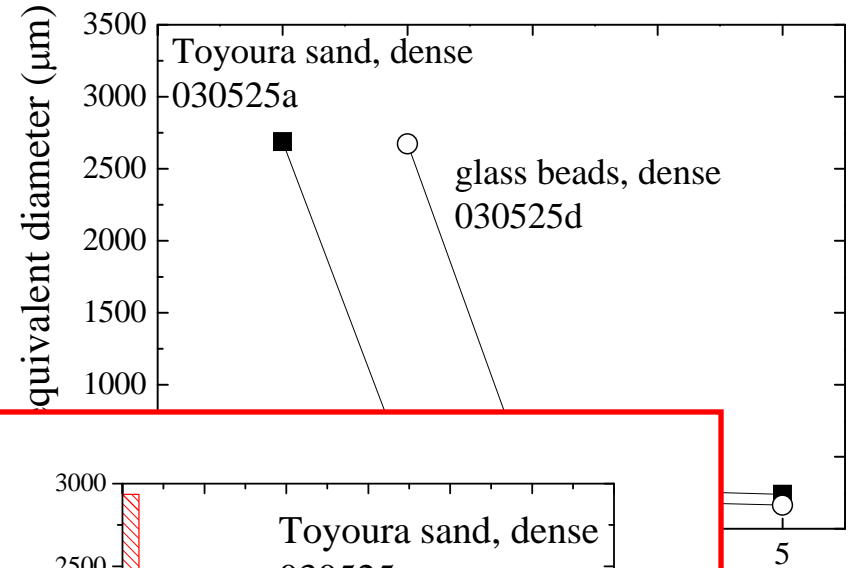
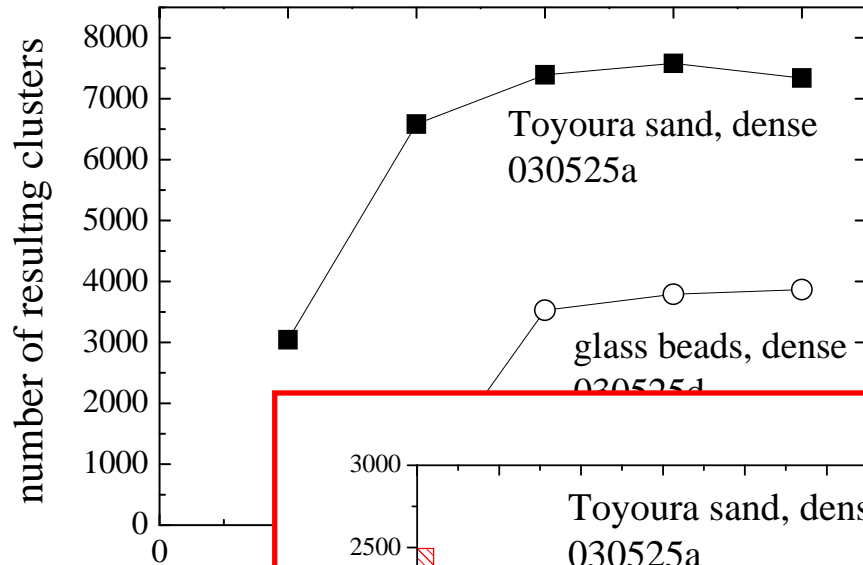
Cluster labeling



Attribution



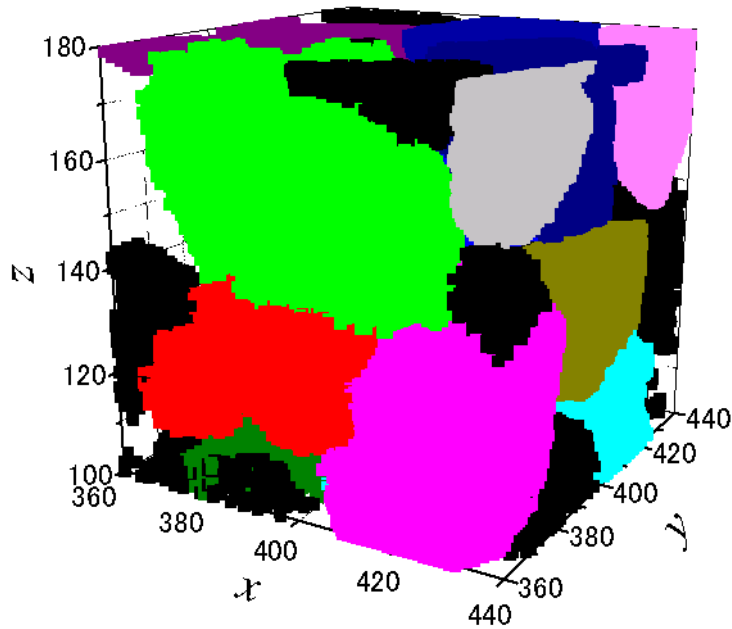
# Adequate erosion cycles







# Grain identification

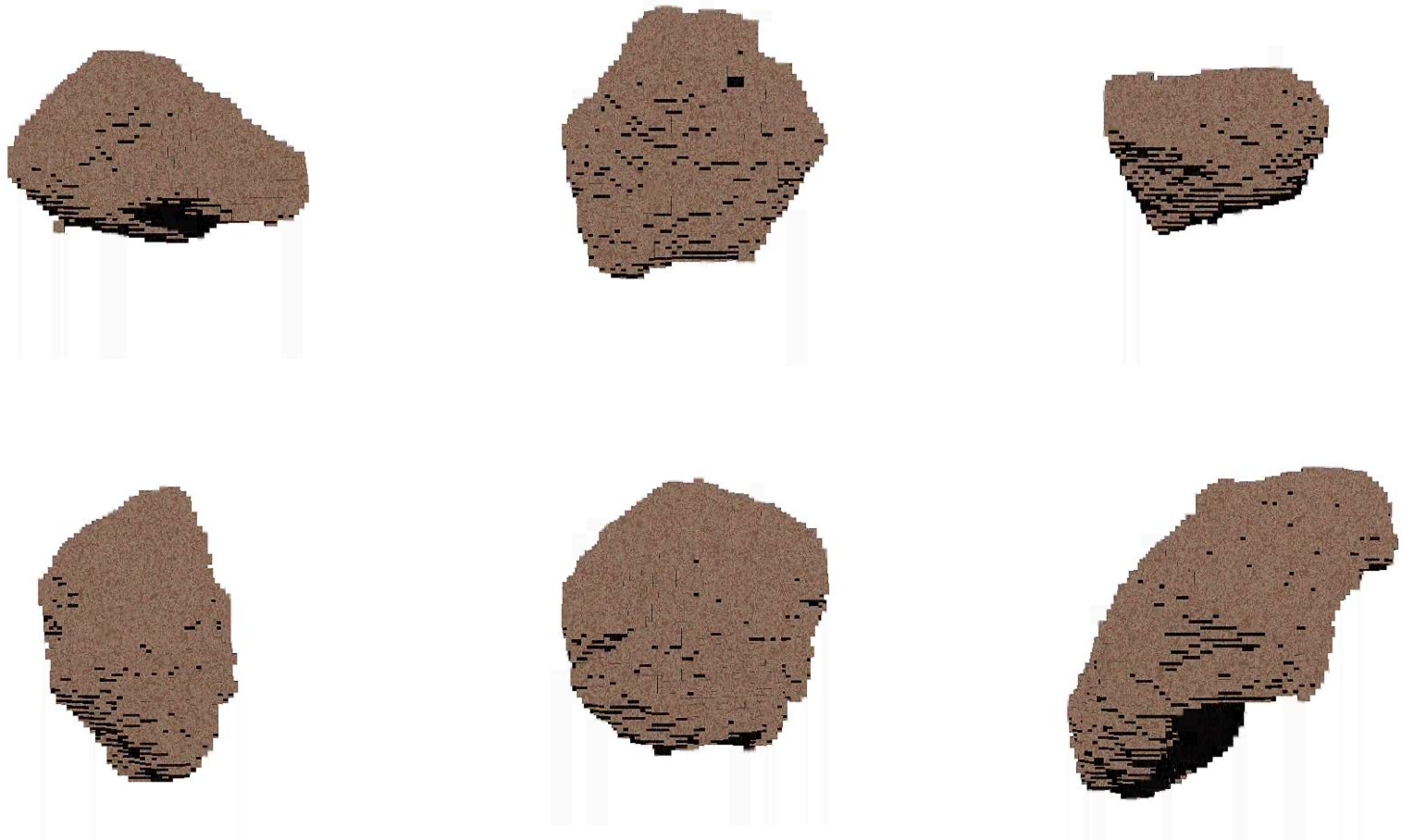


**3-D image after attribution process**



# Grain identification

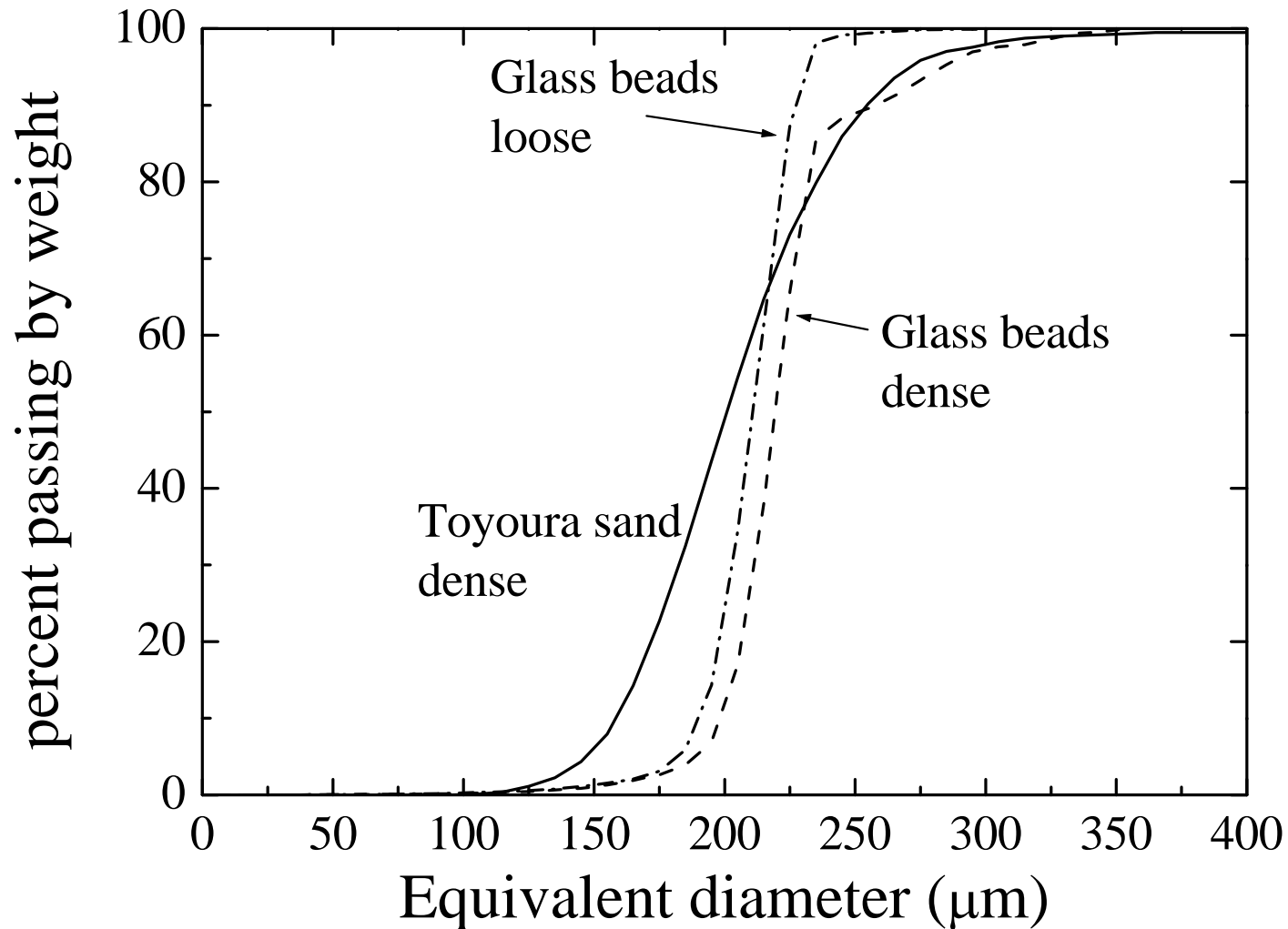
---



**Identified Toyoura sand grains**

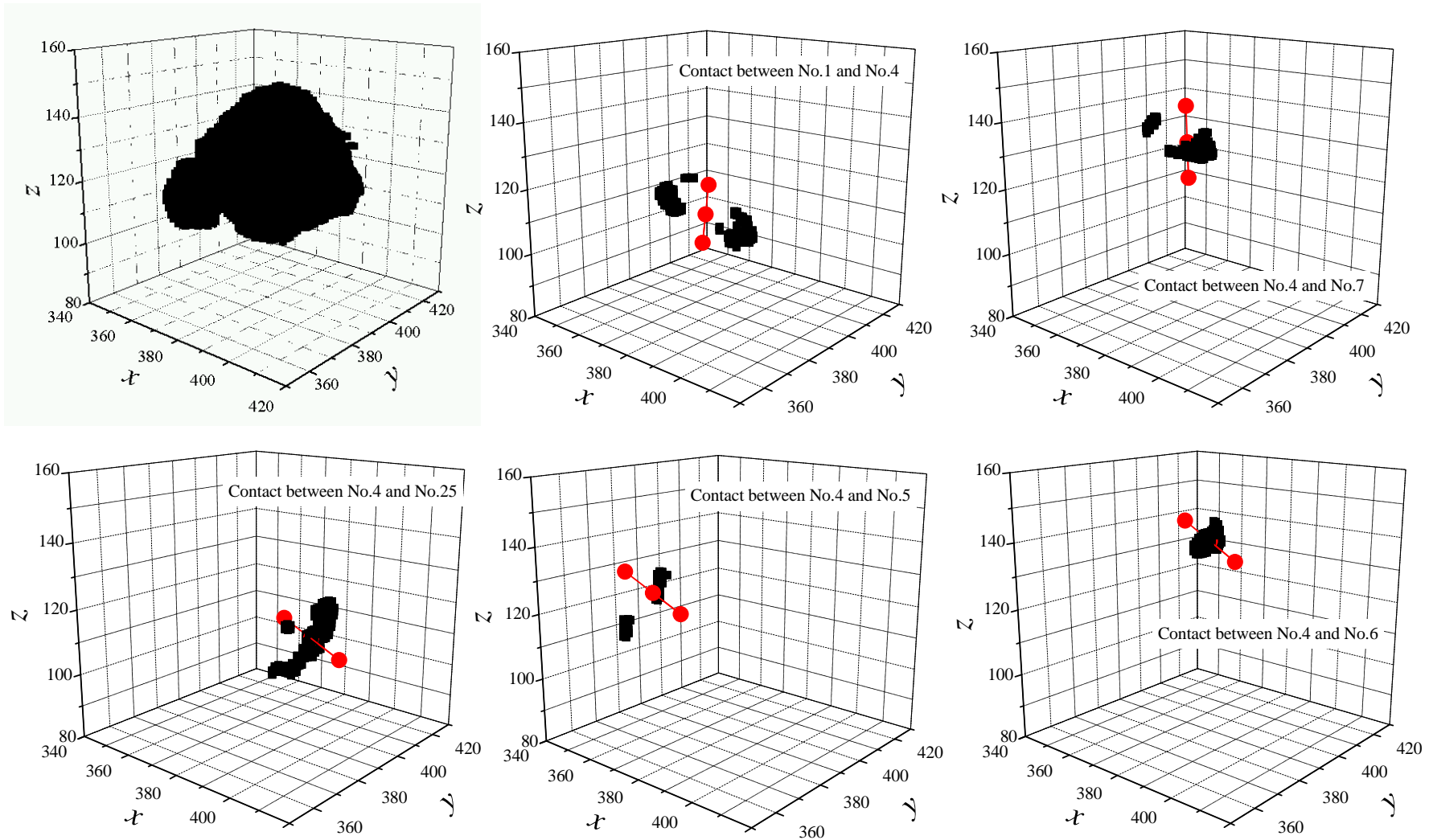


# Grain size distribution





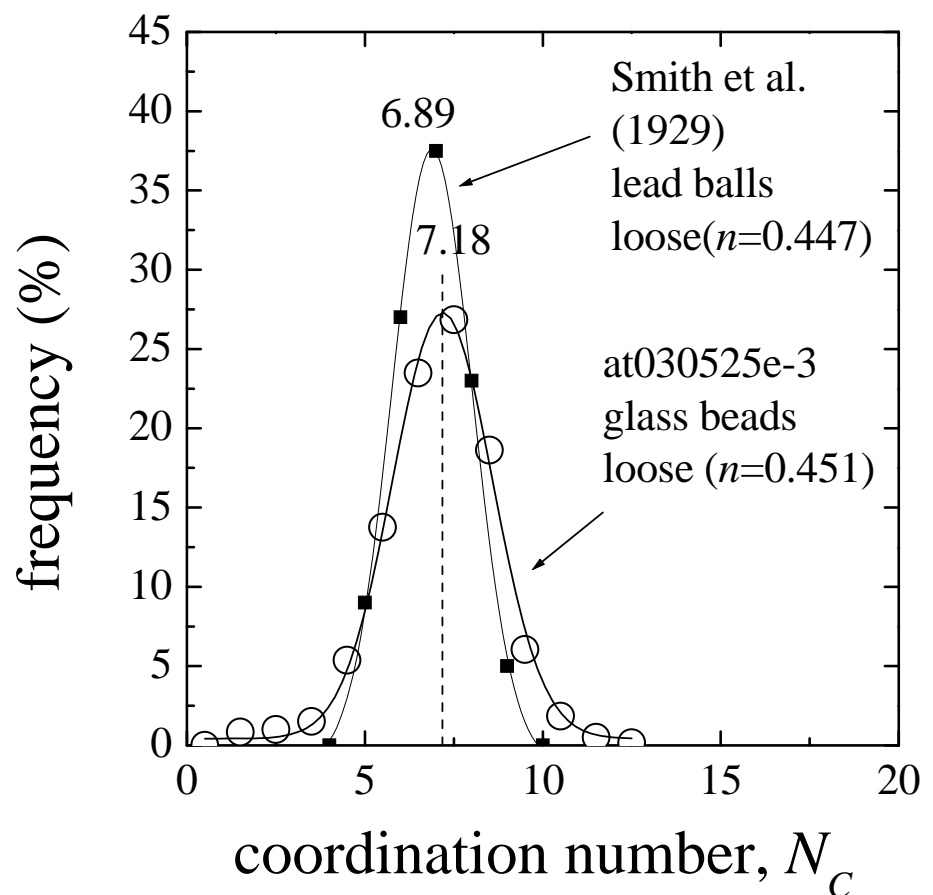
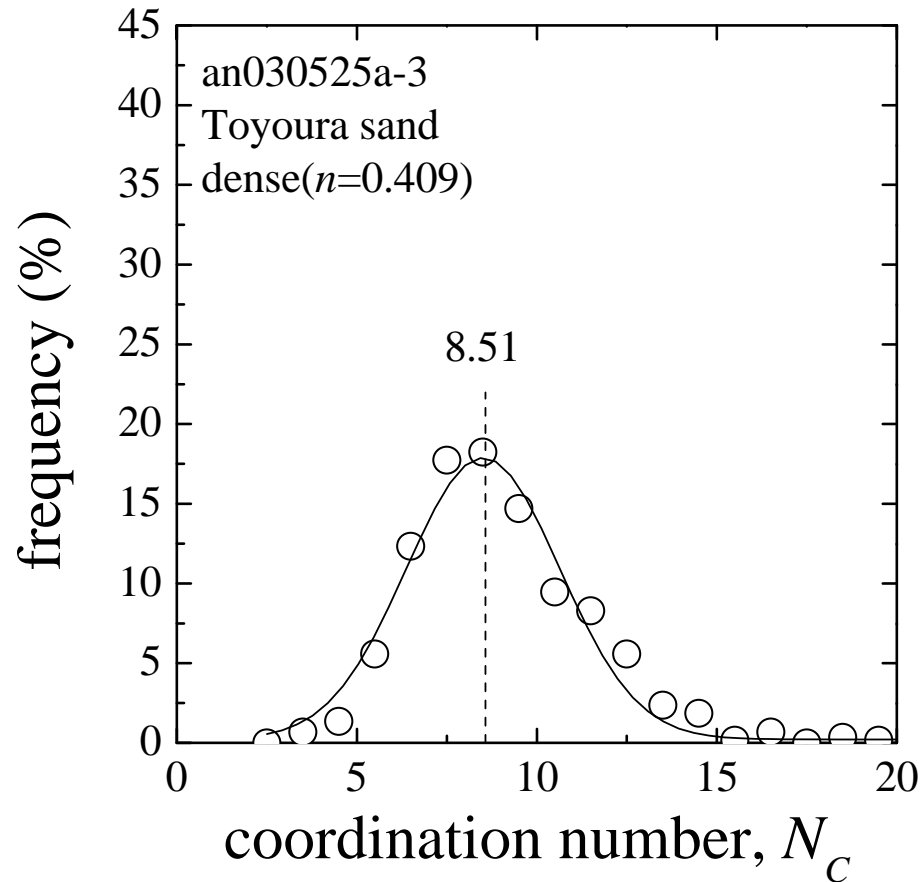
# Contact area and their normals



→ coordination number, fabric tensor, etc.



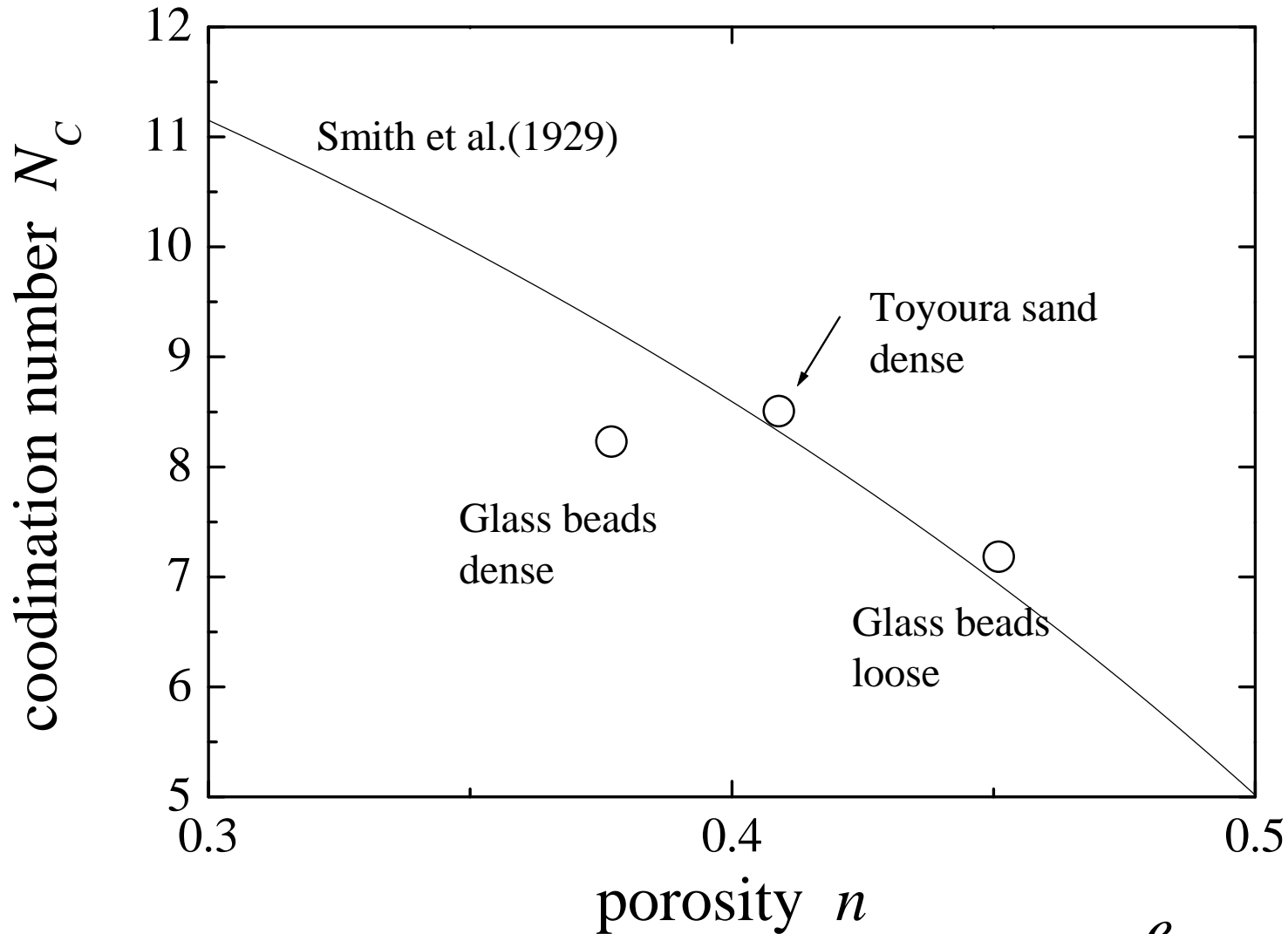
# Coordination number (1)



**like a normal distribution**



# Coordination number (2)



$$n = \frac{e}{e + 1}$$

# Next step

---

**\*Detection of each grain motion  
(translation and rotation)**

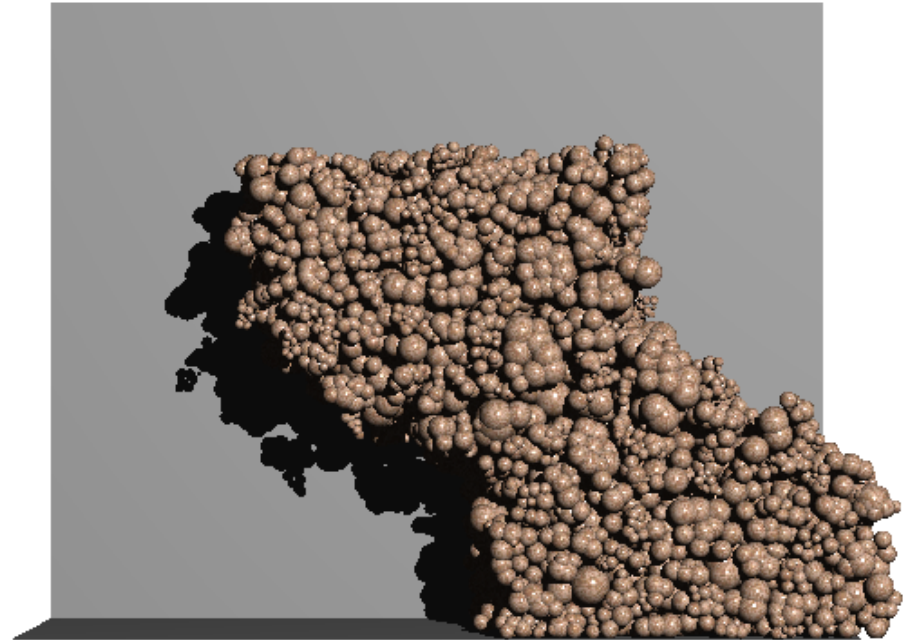
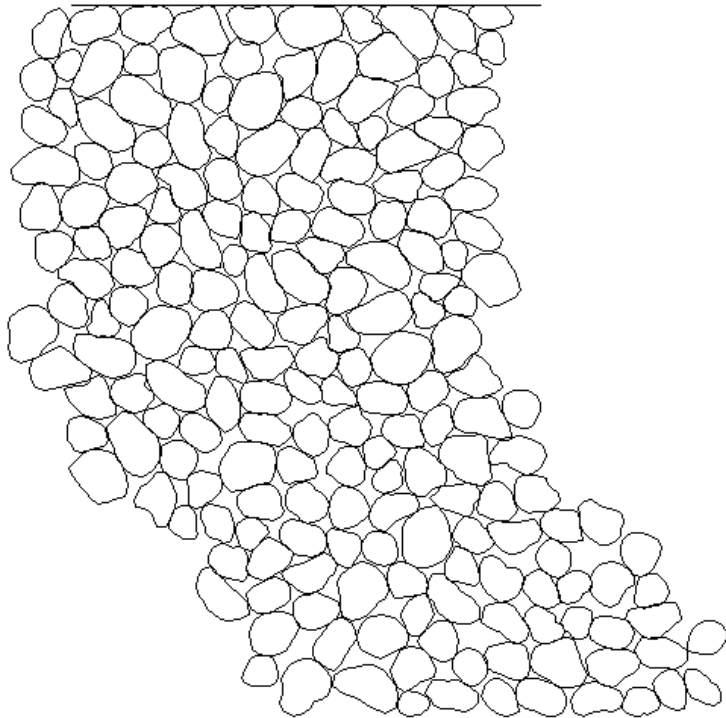
(Chang, Matsushima, Lee, J. Eng. Mech. ASCE, 2002.)

**\*Detection of grain crushing**



# Image-based DEM

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# Background

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- \* **Rapid increase of computer abilities**  
→ **DEM** simulations with large number of grains
- \* **For quantitative discussion...**  
→ **Precise modeling** of grains  
(contact model, grain shape, crushability, etc.)  
is necessary.

This study deals with  
**GRAIN SHAPE MODELING**

# Image-based modeling (Matsushima and Saomoto 2002)

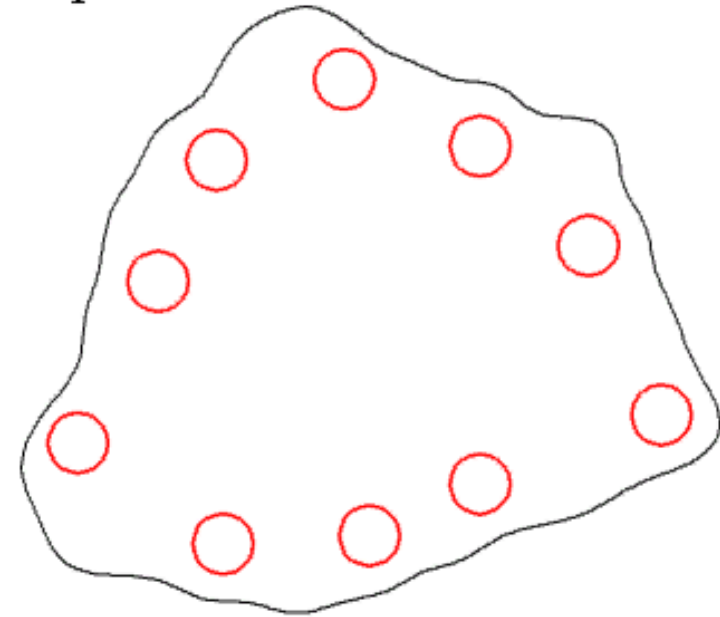
---

Irregular grain shape is described by a **rigid connection of elements** (circles or spheres)

To find an **optimum positions and radii** of the elements...

time marching computation  
(Dynamic optimization)

step=0

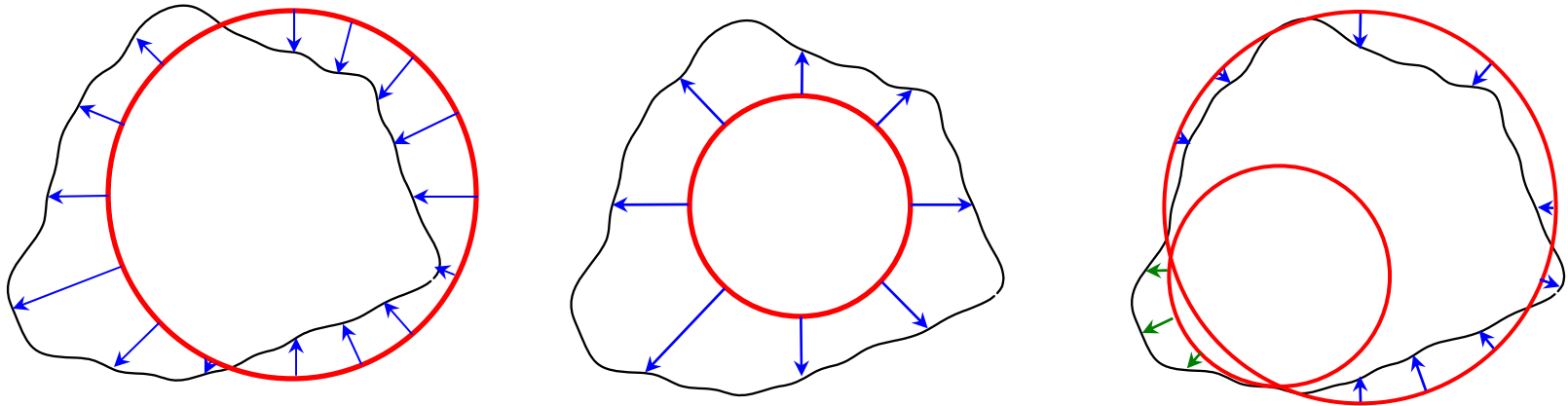


Each element moves and expands (or shrink)  
to get a better fitting to the target grain shape

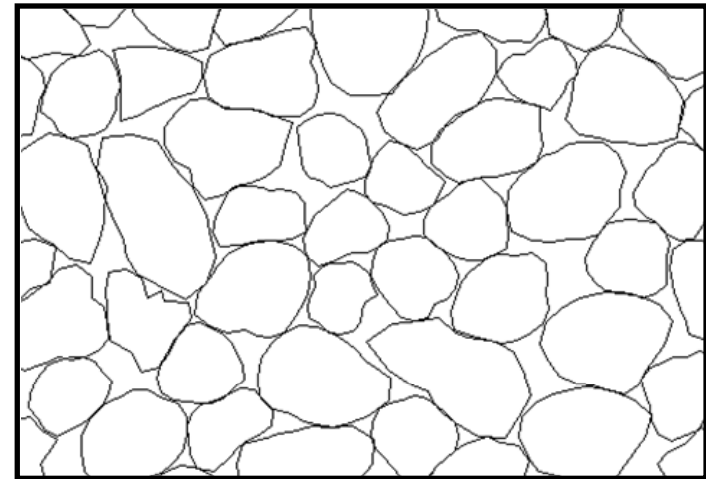
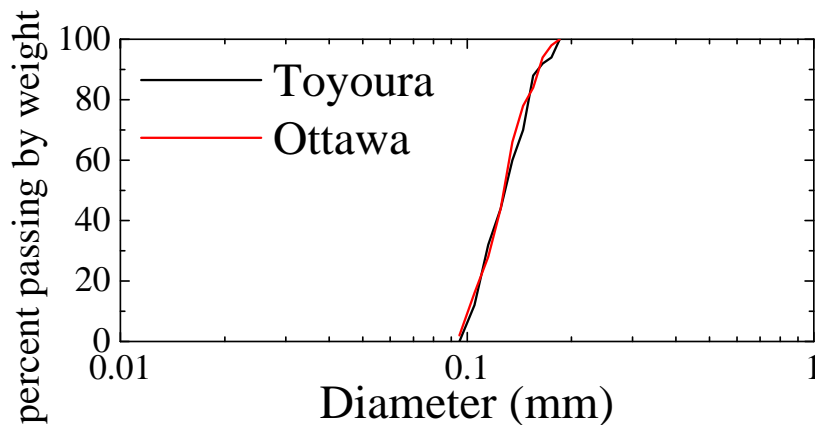
# Dynamic Optimization algorithm

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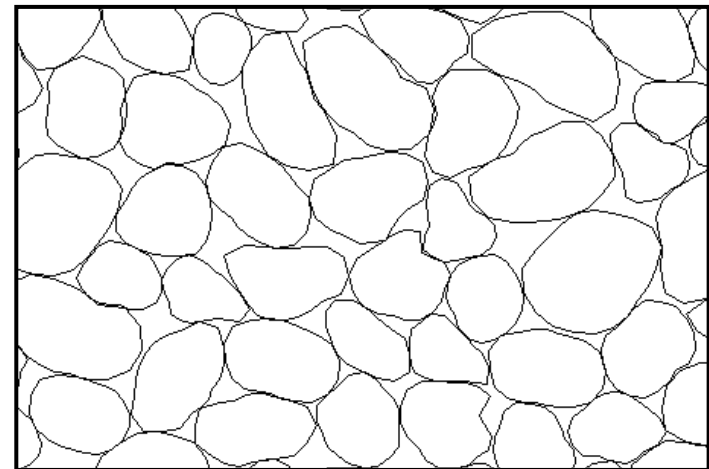
Each surface point of a target grain gives an **attraction** to the closest element which directs from the centroid of the element to the surface point and its magnitude is proportional to the distance.



# 2D example (1)



Toyoura sand (sub-angular)

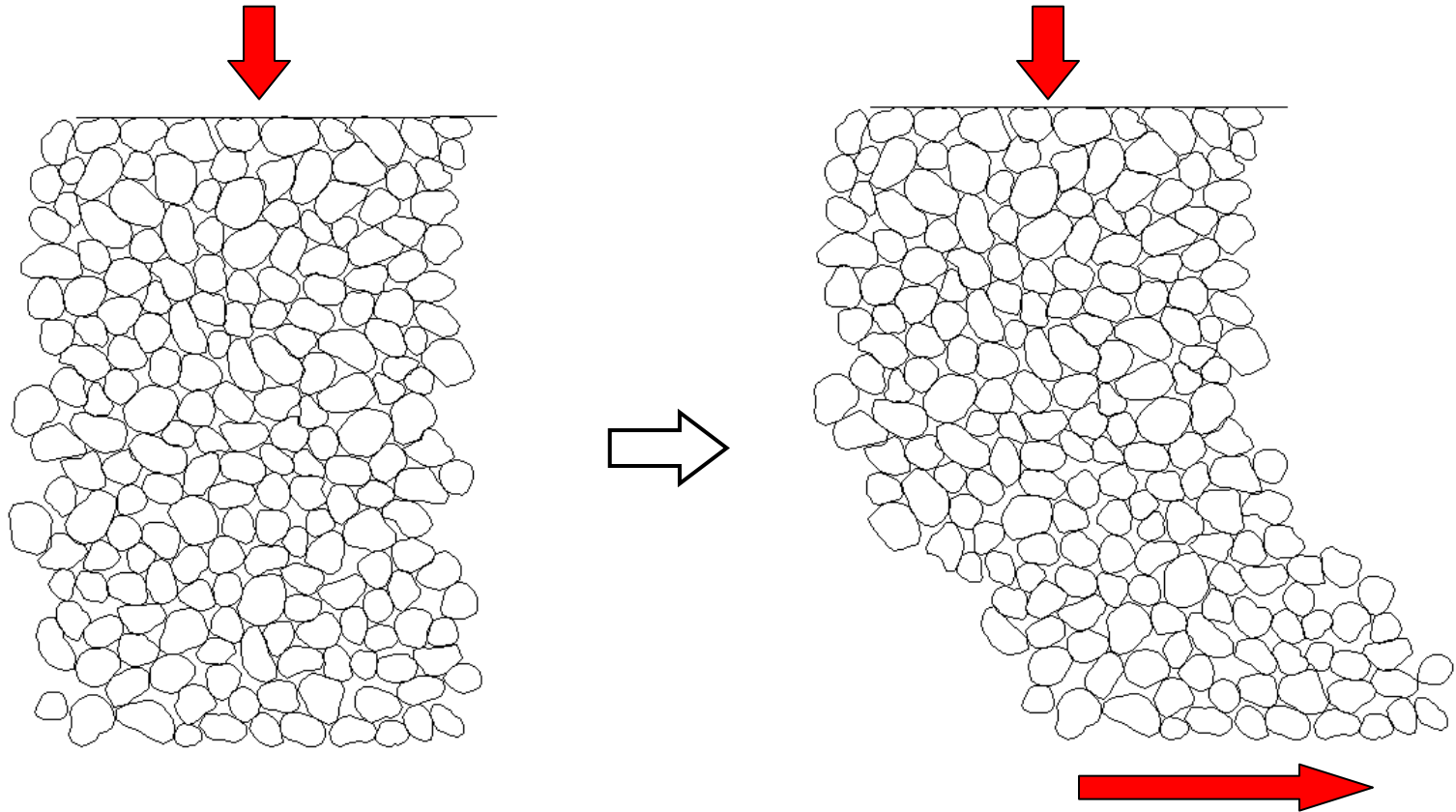


Ottawa sand (sub-rounded)

Grain density	2.64(g/cm <sup>2</sup> )
Spring constant	
(normal)	1.0e9 (g/s <sup>2</sup> )
(tangential)	2.5e8 (g/s <sup>2</sup> )
Damping coefficient	
(normal)	2.0e2 (g/s)
(tangential)	1.0e2 (g/s)
Friction coefficient between grains	27 (deg.)
Time increment	2.5e-8 (sec.)

# 2D example (2)

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**200 grains (Each grain is modeled with 10 elements)**

**Periodic boundary** at both sides

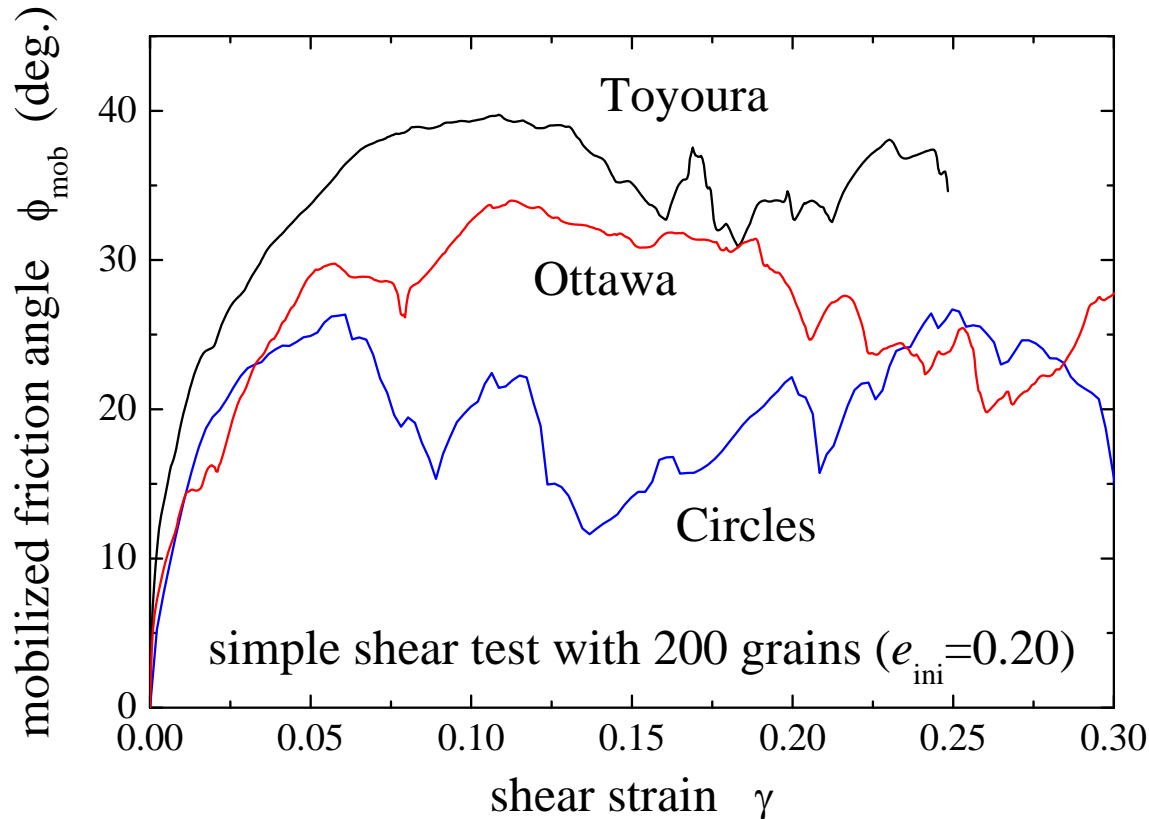
**Constant confining pressure(10kN/m),**

**Lateral displacement is imposed at the bottom grains**



# 2D example (3)

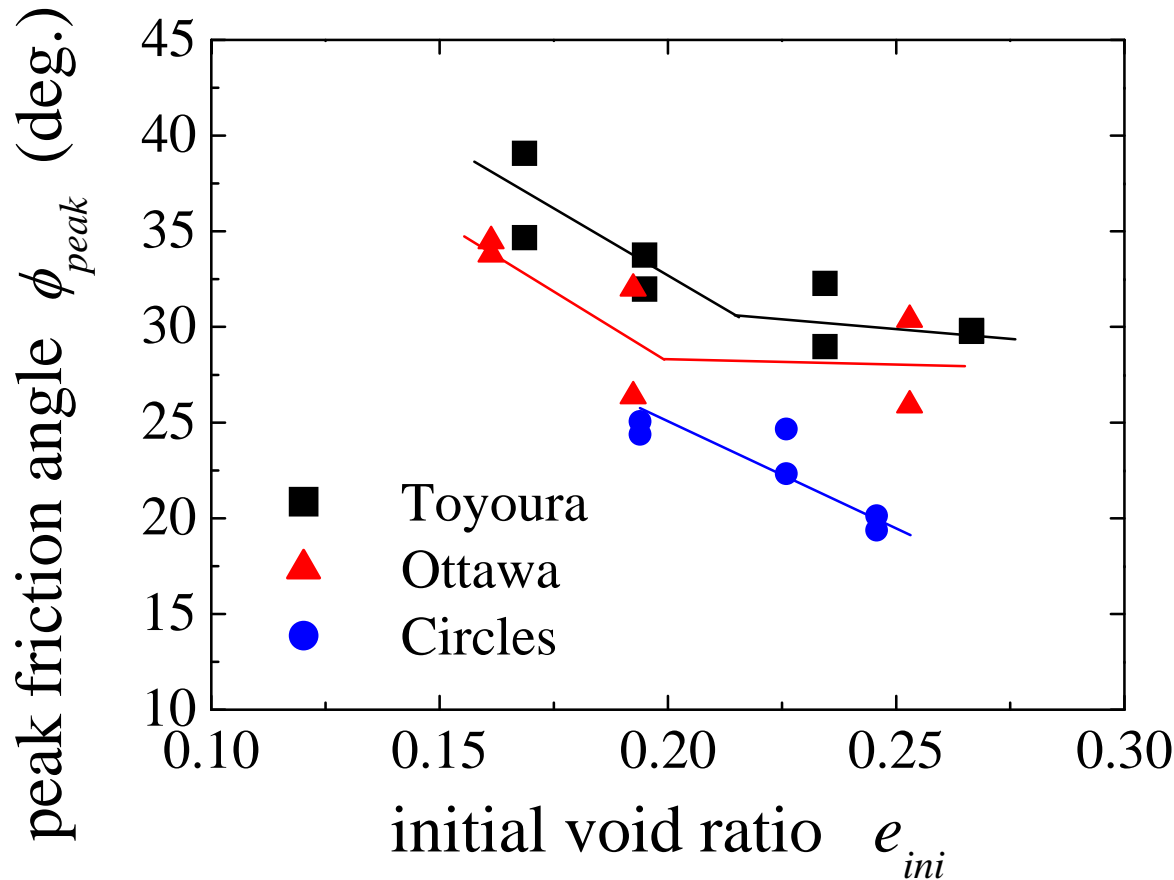
## Dense specimen ( $e_{ini}=0.20$ )



**Toyouira > Ottawa > Circles for peak strength**

# 2D example (4)

## Peak strengths with different initial void ratio

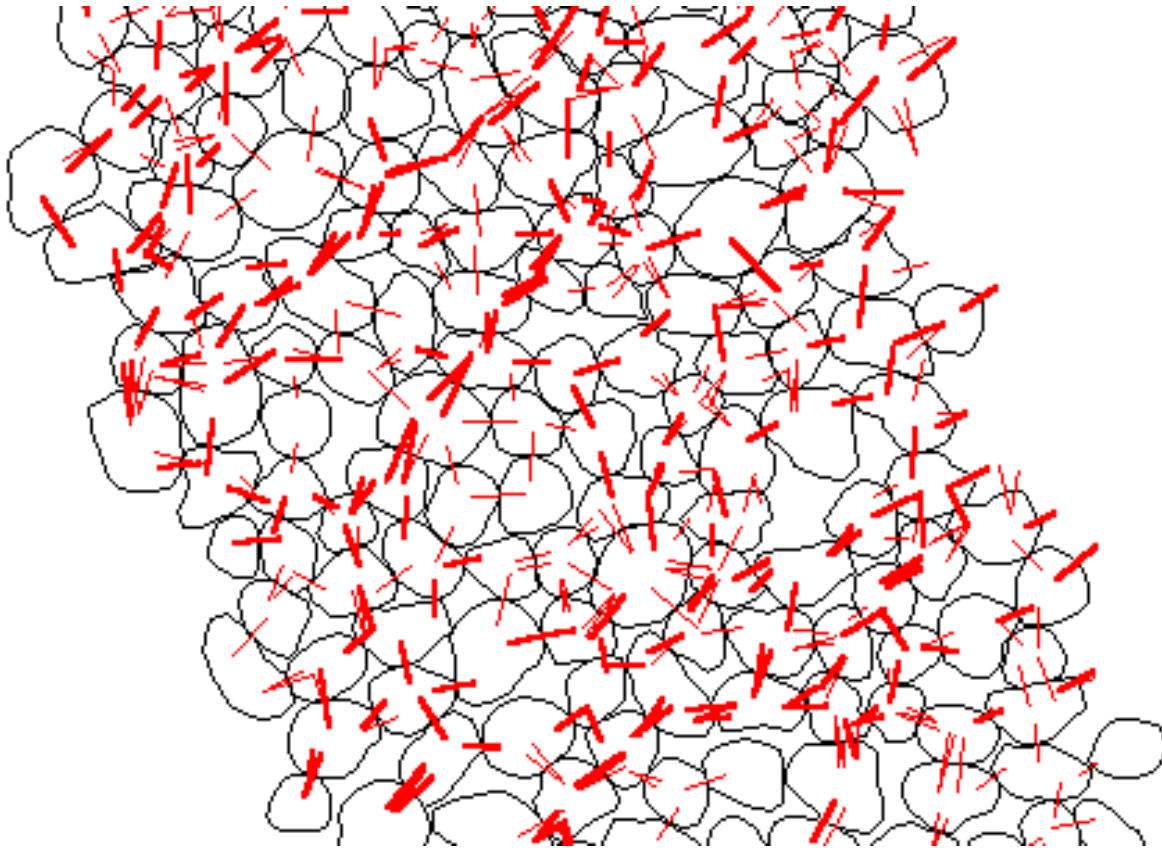


**The modeling is verified qualitatively.**

# 2D example (5)

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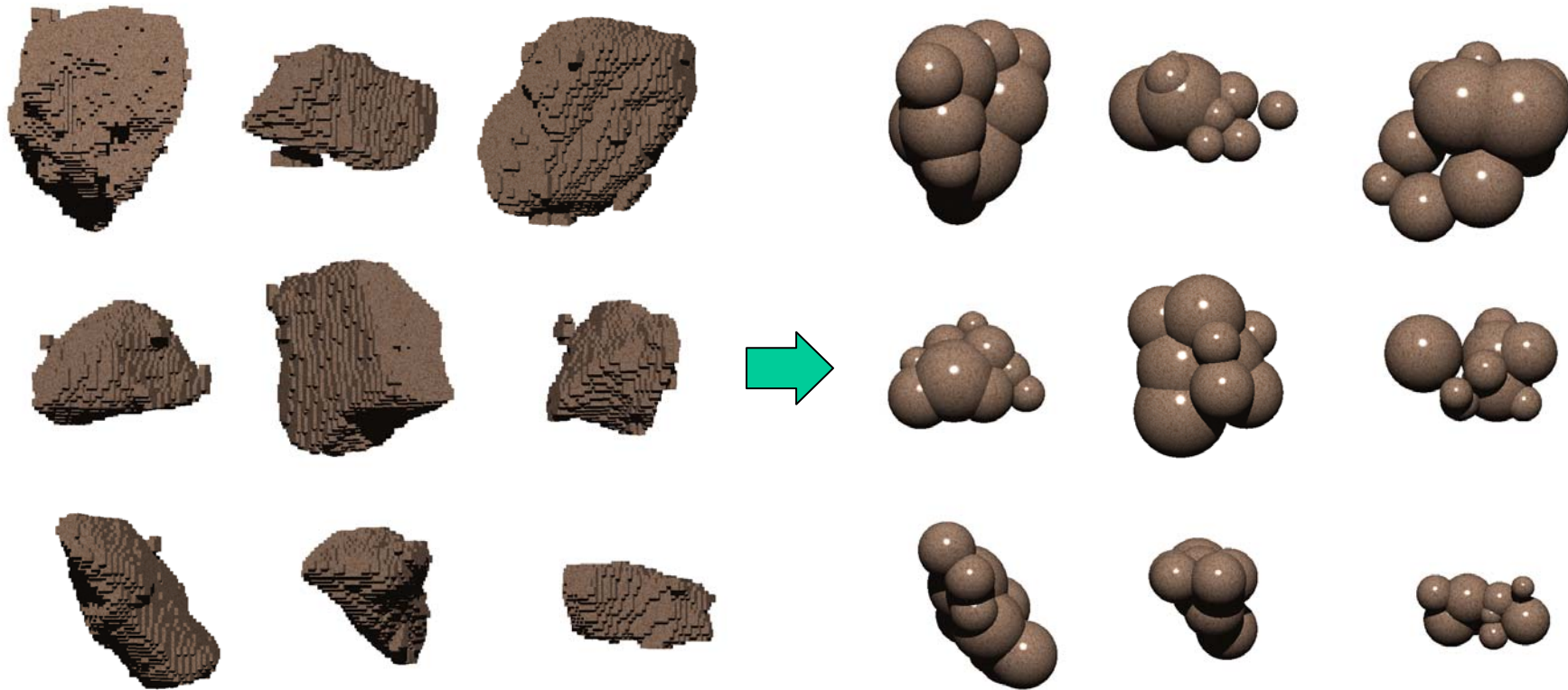
## Granular column structure during shear



**Two grains are in contact with plural points  
→Moment transmission →Higher strength**

# 3D example: Toyoura sand (1)

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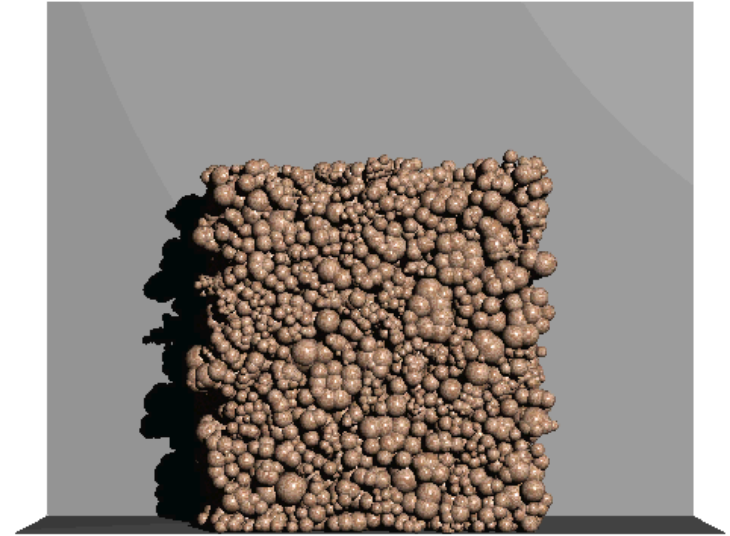
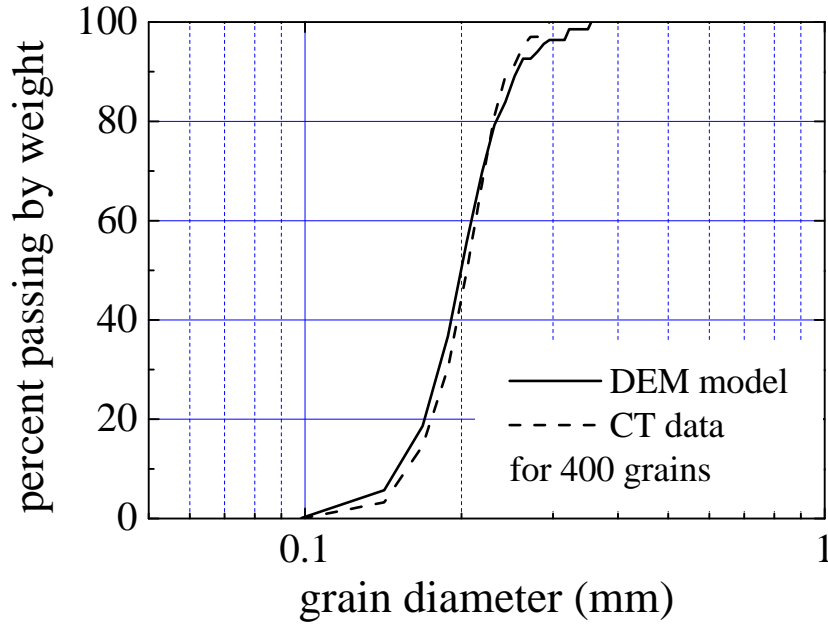
**X-ray CT result**

**3D modeling**

**Toyouira sand model**

# 3D example: Toyoura sand (2)

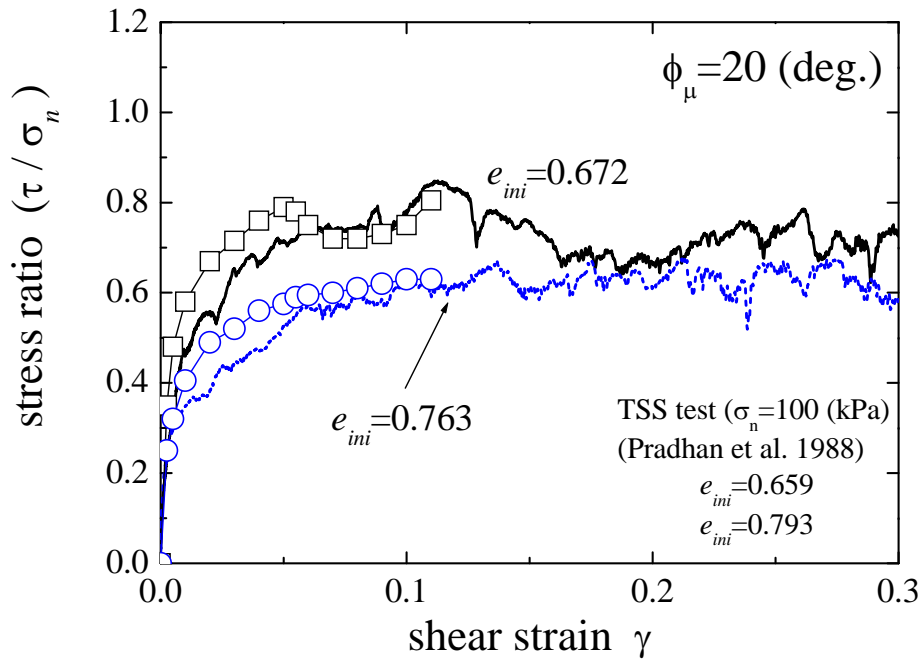
---



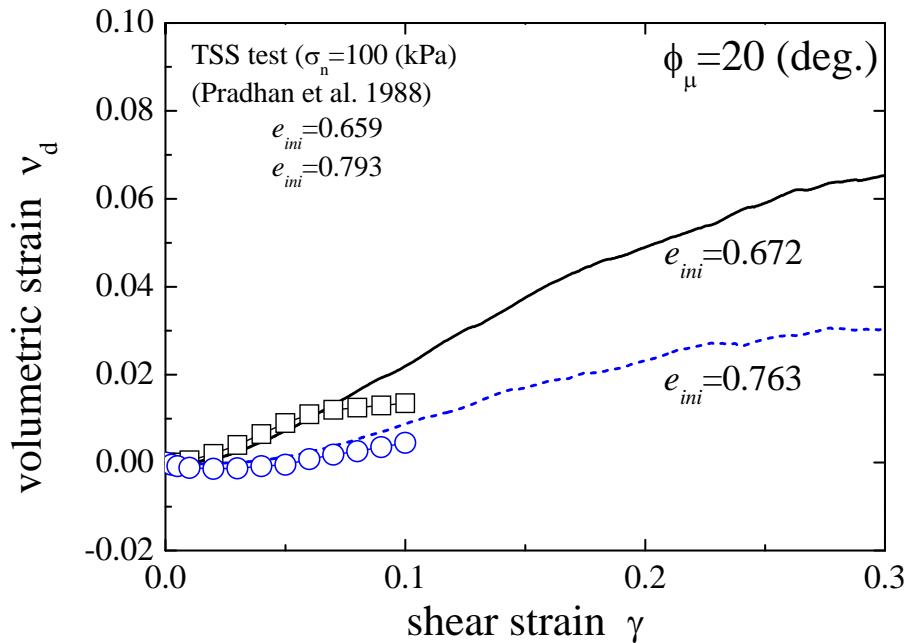
**Grain size distribution:  
DEM model = original CT data**

**Simple shear simulation**

# 3D example: Toyoura sand (3)



Stress-strain curve

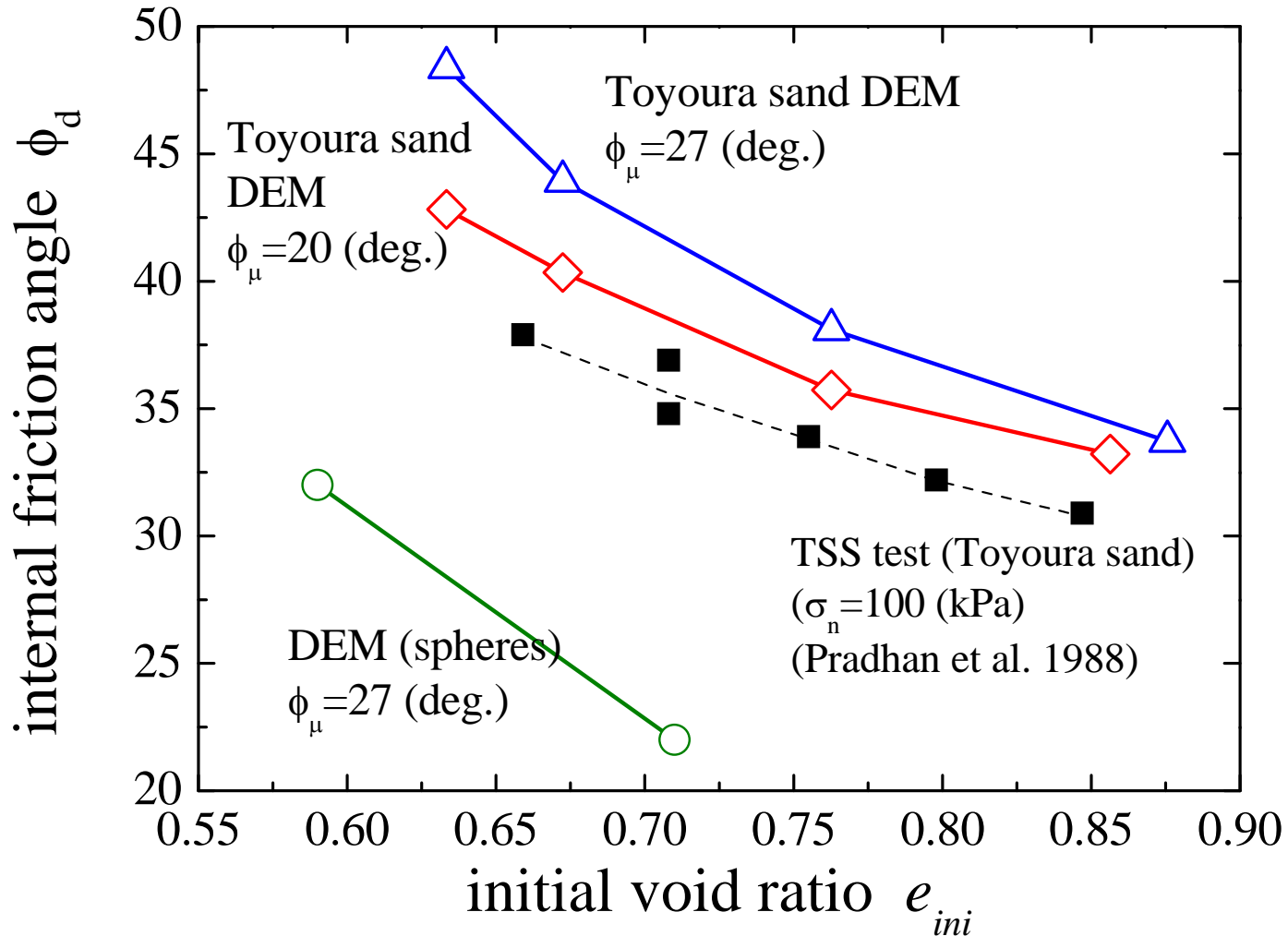


dilation curve

**Quantitative agreement** with experiment  
if inter-particle friction angle=**20**(deg.)



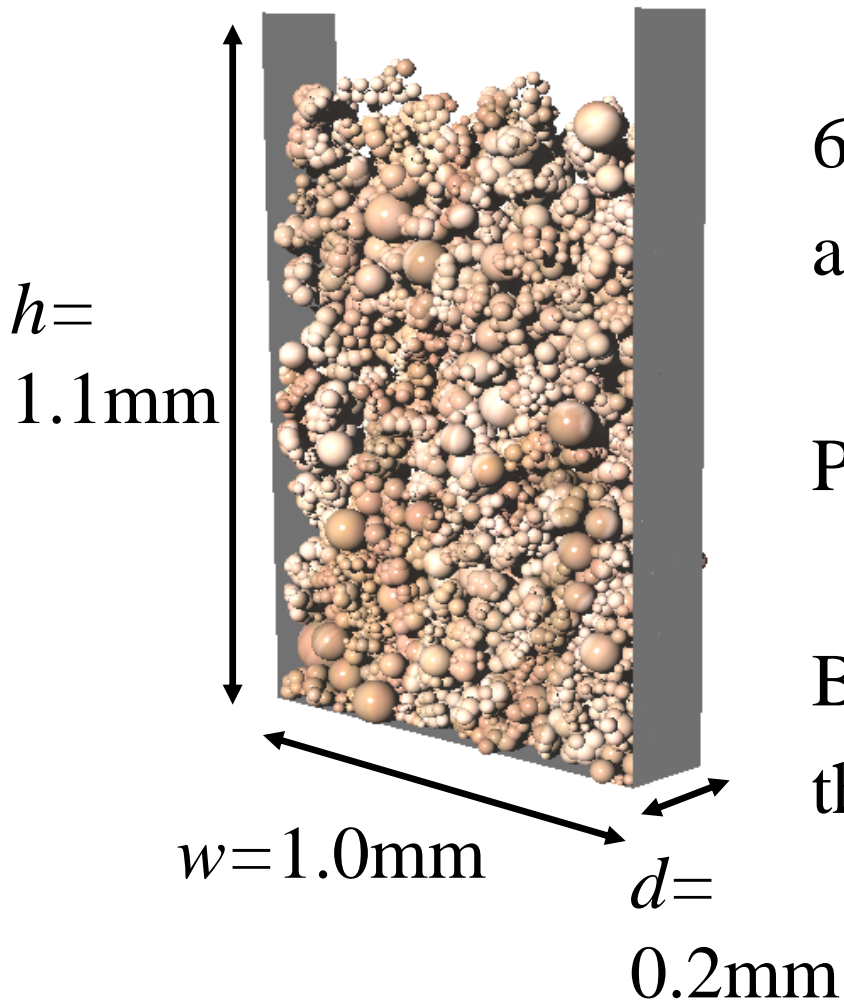
# 3D example: Toyoura sand (4)



**Peak strength for various void ratio**

# Lunar soil simulatant (1)

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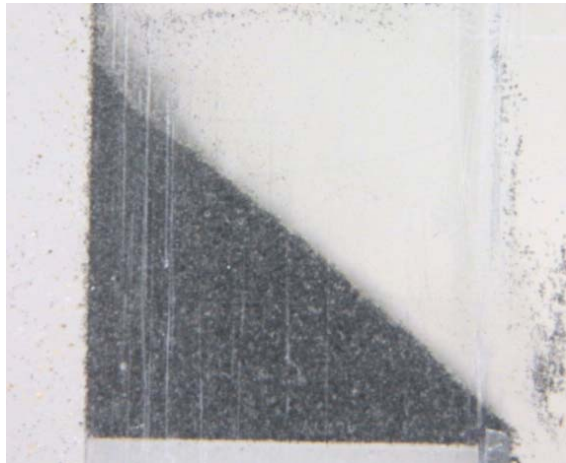
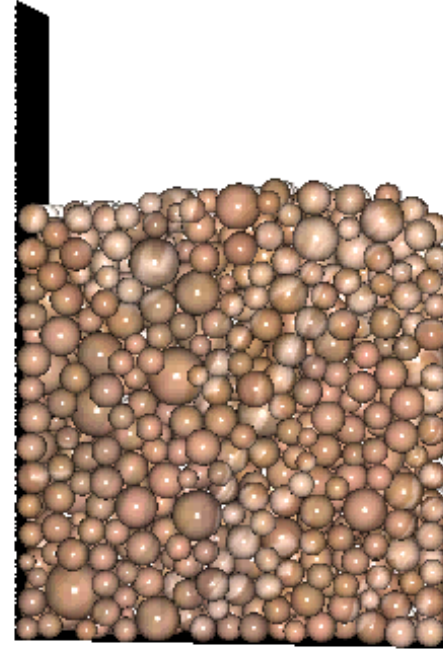
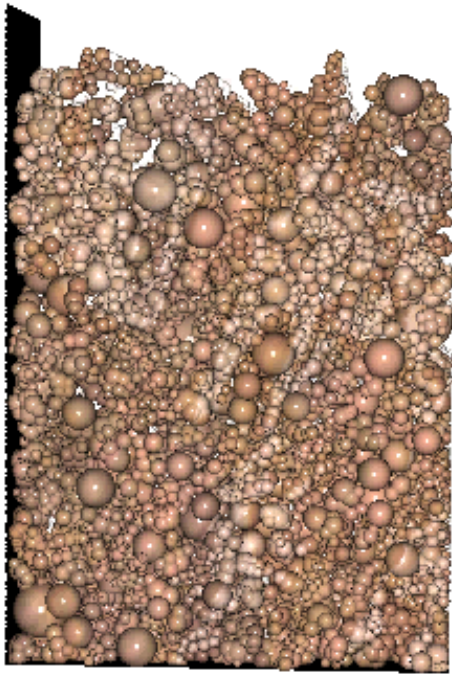


600 grains (10-spheres model)  
are fell down into a vessel

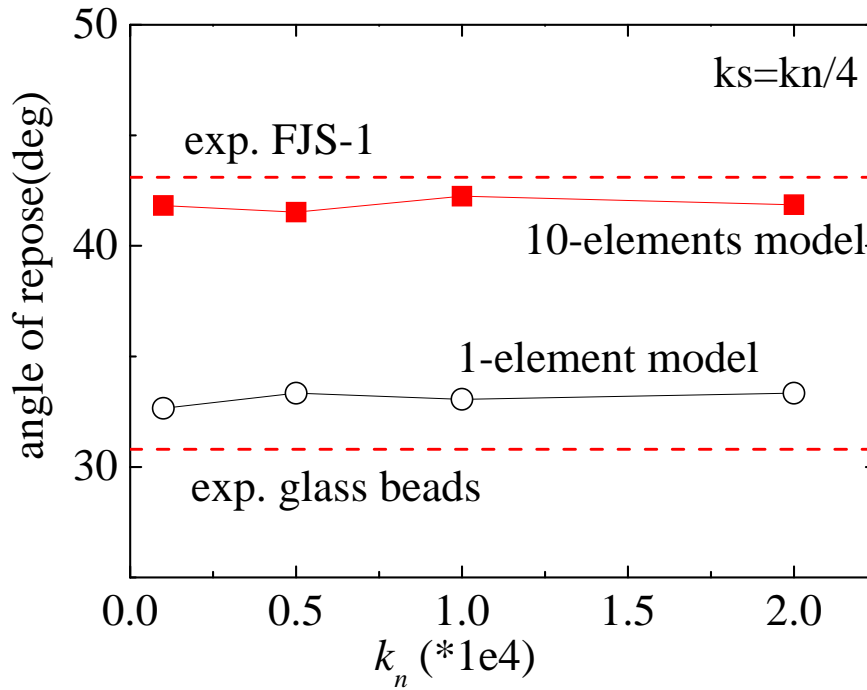
Periodic boundary in y-direction

Bottom grains are fixed into  
the bottom plate

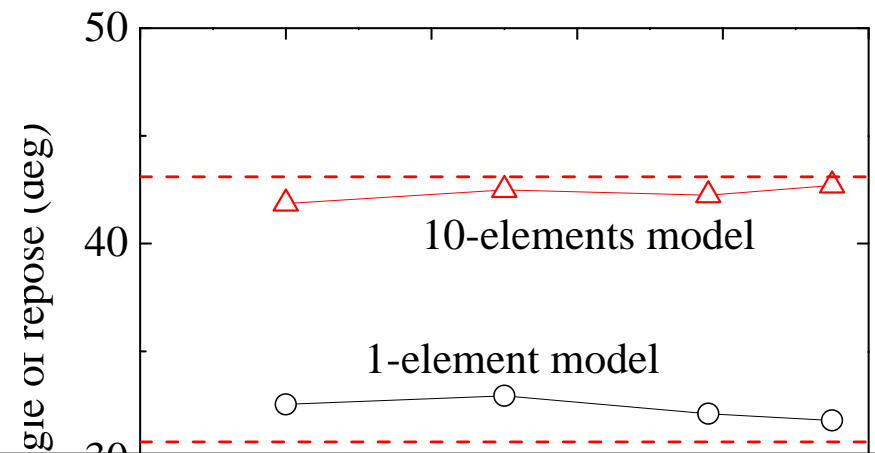
Remove the right side wall



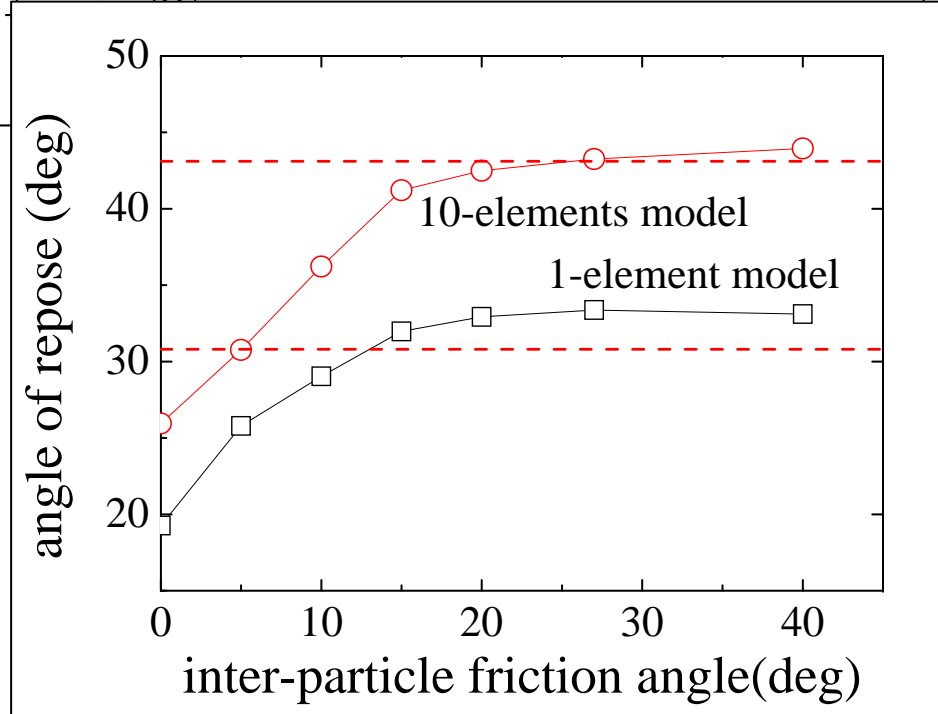
# Lunar soil simulant(3): Parametric study



**Effect of grain hardness**

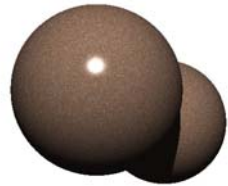


**effect of interparticle friction**

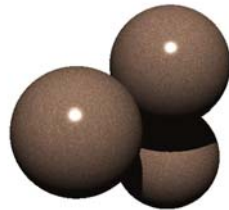


# Lunar soil simulants(4): model accuracy

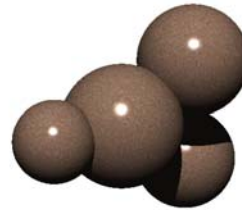
---



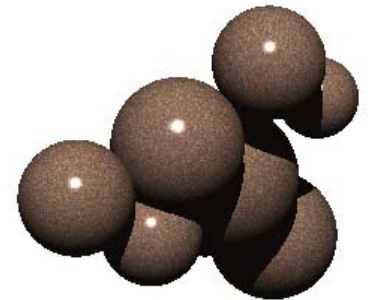
2-elements  
model



3-elements  
model

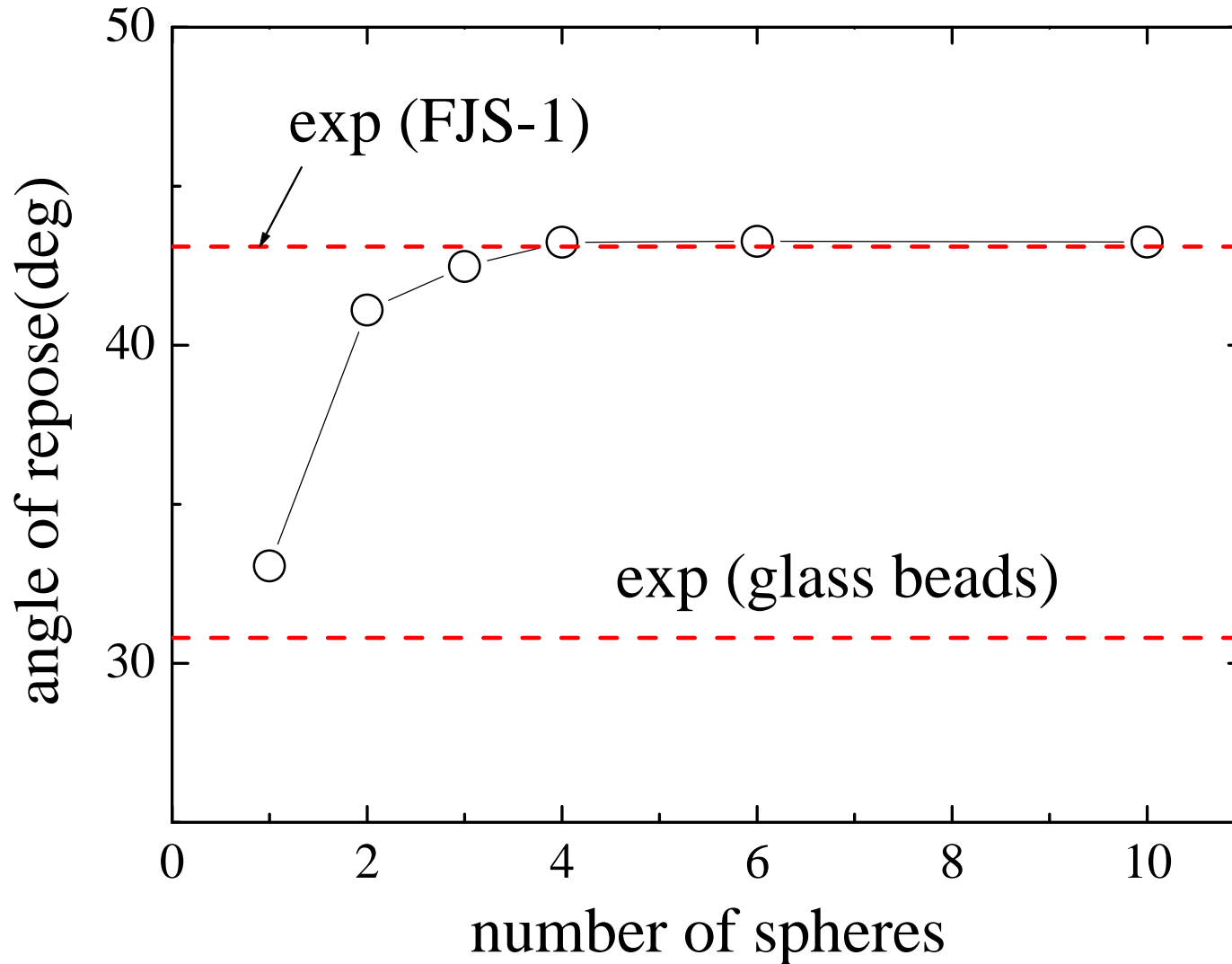


4-elements  
model



7-elements  
model

# Lunar soil simulant(5): model accuracy

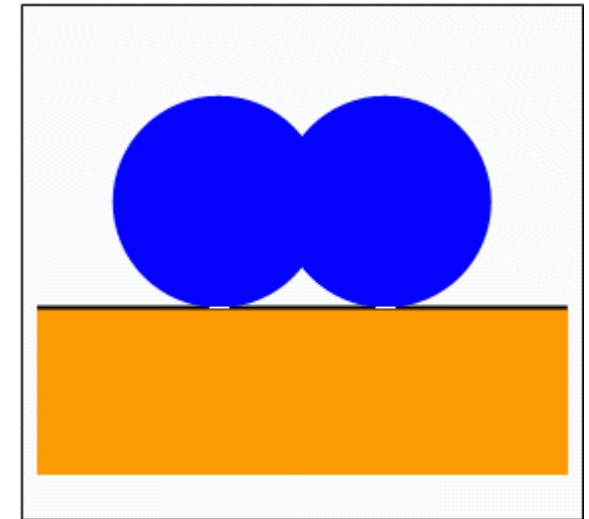
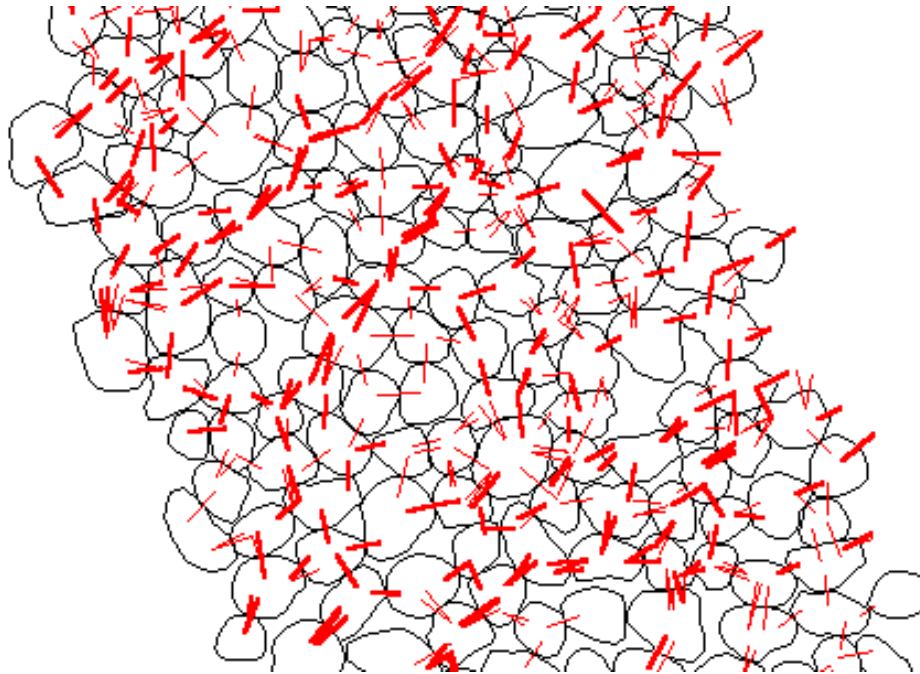




# Particle shape effect: The mechanism

Matsushima, P&G2005

## Contact force chain



**Plural contact points** between two grains

→ **rolling resistance**

→ **overall shape is important**



# Conclusions

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**Application of Granular Mechanics into geomaterials has been tried for decades.**

**Some breakthrough has been found recently (in my opinion).**

**Recent progress of various technologies makes it push forward.**

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