# Impact Analysis of Space Structure due to Collision with Hypervelocity Space Debris by using ASI-FEM

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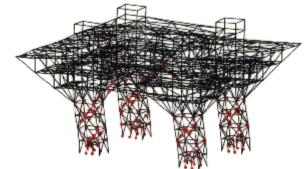
Prediction of damage against space debris collisions

Numerical approach

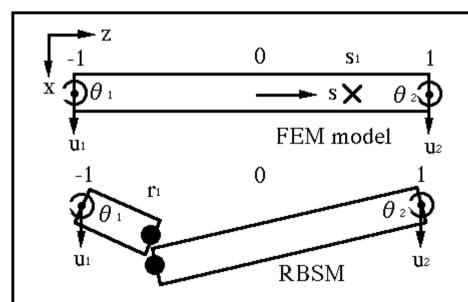
Strong non-linearity and discontinuity

# Adaptively Shifted Integration (ASI) technique

- Very clear physical meanings
   comparing strain energy approximations
   FEM model RBSM(Rigid-Bodies Spring Model)
- Simplicity easy to implement into FEM codes



 Low computational cost accurate solutions by minimum number of elements



- X Numerical integration point
- Rotational and shear spring connecting rigid bars (plastic hinge)

Fig.1 Linear Timoshenko beam element and its physical equivalent

Relation between the location of a numerical integration point and a plastic hinge

$$s_1 = -r_1 \ or \ r_1 = -s_1$$

where

s1:position of a numerical integration point

r1:position of a plastic hinge or a fractured section

## **Incremental stiffness matrix and initial stress matrix**

### Elastically deformed element

$$\begin{bmatrix} {}^{n}\bar{K}_{L} \end{bmatrix} = \int_{n_{l}} {}^{u}T ]^{T} \cdot {}^{0}T ]^{T} {}^{n}\bar{B}_{L}(0) ]^{t} [D^{e}(0)] {}^{n}\bar{B}_{L}(0) ]^{0}T \cdot {}^{u}T ]dl$$

$$\begin{bmatrix} {}^{n}\bar{K}_{NL} \end{bmatrix} = \int_{n_{l}} {}^{u}T ]^{T} \cdot {}^{0}T ]^{T} {}^{n}\bar{G}(0) ]^{t} {}^{n}\bar{S}(0) ] {}^{n}\bar{G}(0) ]^{0}T \cdot {}^{u}T ]dl$$

Element with a plastic hinge at its left end

$$\begin{bmatrix} {}^{n}\bar{K}_{L} \end{bmatrix} = \int_{n_{l}} {}^{u}T \end{bmatrix}^{T} \cdot {}^{0}T \end{bmatrix}^{T} {}^{n}\bar{B}_{L}(1) ]^{t} [D^{p}(-1)] {}^{n}\bar{B}_{L}(1) ]^{0}T \cdot {}^{u}T ]dl$$

$$\begin{bmatrix} {}^{n}\bar{K}_{NL} \end{bmatrix} = \int_{n_{l}} {}^{u}T ]^{T} \cdot {}^{0}T ]^{T} {}^{n}\bar{G}(1) ]^{t} {}^{n}\bar{S}(-1) ] {}^{n}\bar{G}(1) ]^{0}T \cdot {}^{u}T ]dl$$

Internal force vector (elastic element)

$${n \choose n} = \int_{n} [{}^{0}T]^{T} \cdot [{}^{u}T]^{T} \cdot [{}^{n}\bar{B}_{L}(0)]^{T} \cdot {n \over n} \bar{R}(0) dl$$

Released force vector (fully-plastic or fractured element)

$${n \choose n} = \int_{n} [{}^{0}T]^{T} \cdot [{}^{u}T]^{T} \cdot [{}^{n}\bar{B}_{L}(1)]^{T} \cdot {n \over n} \bar{R}(-1) dl$$

## Criteria for member fracture

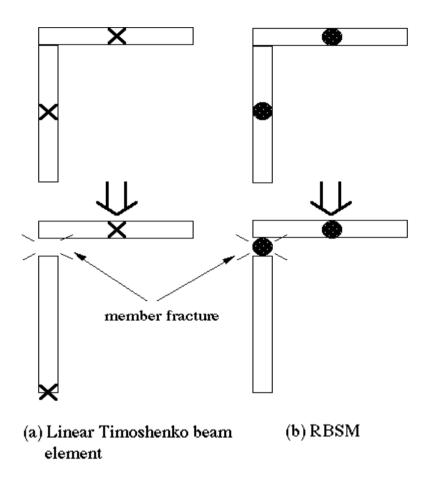


Fig. Member fracture in the ASI technique

$$\left(\frac{\kappa_x}{\kappa_{fx}}\right) - 1 \ge 0, \quad \left(\frac{\kappa_y}{\kappa_{fy}}\right) - 1 \ge 0,$$

$$\left(\frac{\varepsilon_z}{\varepsilon_{fz}}\right) - 1 \ge 0$$

$$\left(\frac{\varepsilon_z}{\varepsilon_{fz}}\right) - 1 \ge 0$$

 $\kappa_{fx}, \, \kappa_{fy}$ : critical curvature around

 $\mathbf{x}$ - and  $\mathbf{y}$ -axes  $\varepsilon_{fz}$ : critical strain

- X Numerical integration point
- Rotational and shear springs connecting rigid bars

# Conditions for the elements in contact algorithm

## Four nodes on a same plane from the initial stage

$$f(x,y,z) \equiv \{(y_{i1}-y_{f2})(z_{i2}-z_{f2})-(y_{i2}-y_{f2})(z_{i1}-z_{f2})\}(x_{f1}-x_{f2}) + \{(x_{i2}-x_{f2})(z_{i1}-z_{f2})-(x_{i1}-x_{f2})(z_{i2}-z_{f2})\}(y_{f1}-y_{f2}) + \{(x_{i1}-x_{f2})(y_{i2}-y_{f2})-(x_{i2}-x_{f2})(y_{i1}-y_{f2})\}(z_{f1}-z_{f2}) \}$$

## and existing in a specific distance

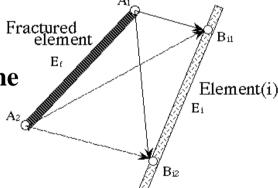
$$|\overline{A_1B_{i1}}| + |\overline{A_1B_{i2}}| \le L_i, \quad |\overline{A_2B_{i1}}| + |\overline{A_2B_{i2}}| \le L_i$$



$$f(x, y, z) \le 5.0 \times 10^6$$

## and existing in a specific distance

$$|\overline{A_1B_{i1}}| + |\overline{A_1B_{i2}}| + |\overline{A_2B_{i1}}| + |\overline{A_2B_{i2}}| \le 1.8(L_f + L_i)$$



= 0

Fig.2a Contact conditions for a fractured element

# Binding conditions for the gap elements

- Four gap elements between the two elements in contact
- Same material properties with other elements
- Stiffness decreases after certain time steps

 $(1.0 \times 10^{-3} \text{ sec})$ 

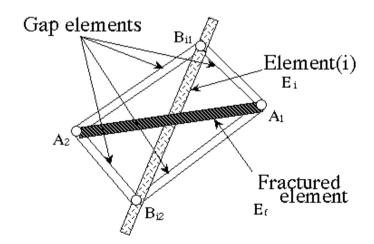


Fig.2b Gap elements in contact algorithm

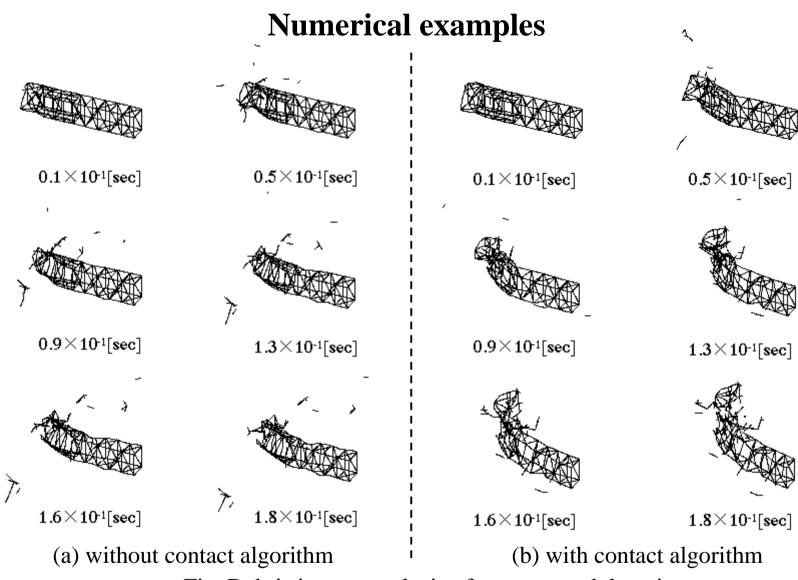
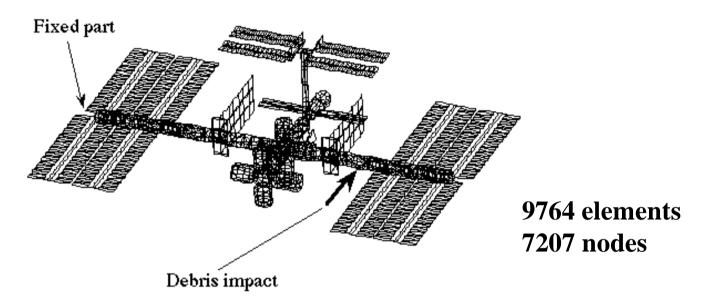


Fig. Debris impact analysis of a space module unit (5 km/sec)

# **Debris impact analysis of ISS**



**Debris** 

mass: 10 kg

velocity: 5 km/sec

Critical values for member fracture

$$\kappa_{fx} = \kappa_{fy} = 1.0 \times 10^{-3}$$
$$\varepsilon_{fz} = 3.0 \times 10^{-1}$$

Fig.3 Analyzed model of ISS

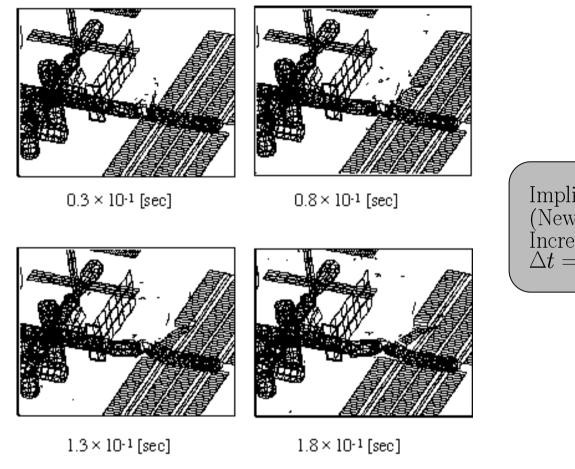


Fig.4 Hypervelocity debris impact analysis of ISS

Implicit scheme (Newmark's  $\beta$  method) Incremental time:  $\Delta t = 0.4 \times 10^{-4} \text{ sec}$ 

## **Concluding remarks**

**ASI technique** 

**Debris impact analysis** 

Practical expression of the damage process

Strong nonlinear (discontinuous) problems easily analyzed by FEM

•• may be applied to Structural design process of space structures